



Geometry Intelligence and Fast RBF for Real-Time CAE Optimisation

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Founder of RBF Morph srl





Agenda

- About Us – Past And Running Projects
- Radial Basis Functions – Data Science And Geometrical Intelligence
- Parameter-Based And Parameter-Free Shape Optimisation
- Digital Engineering
- Two Industrial Examples: Dallara Formula Car, Vespa Engine
- Conclusions
- Next Steps



dallara



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About Us

Past and Running Projects





Research Team at rbfLAB



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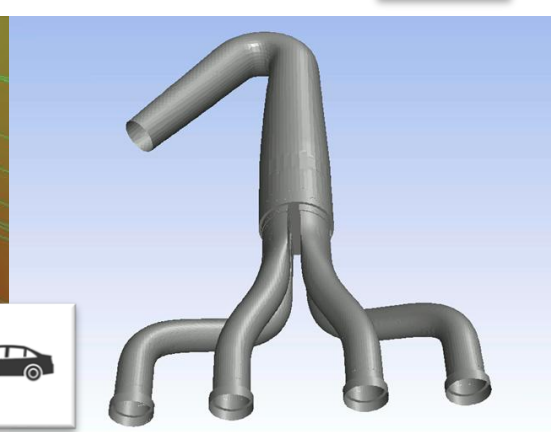
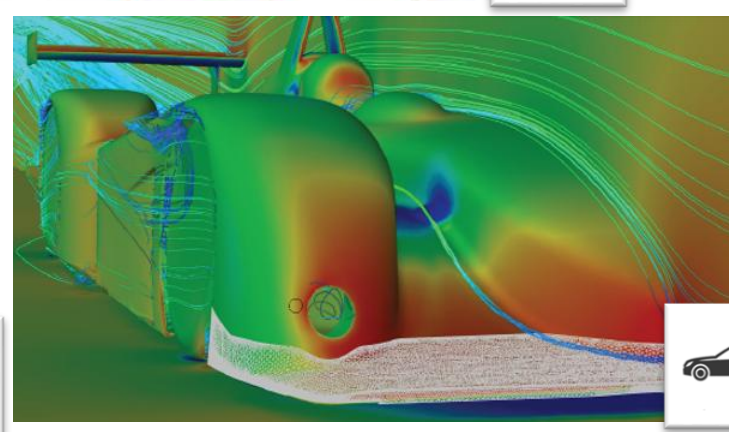
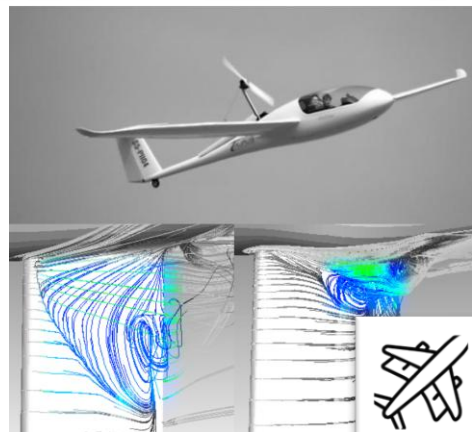
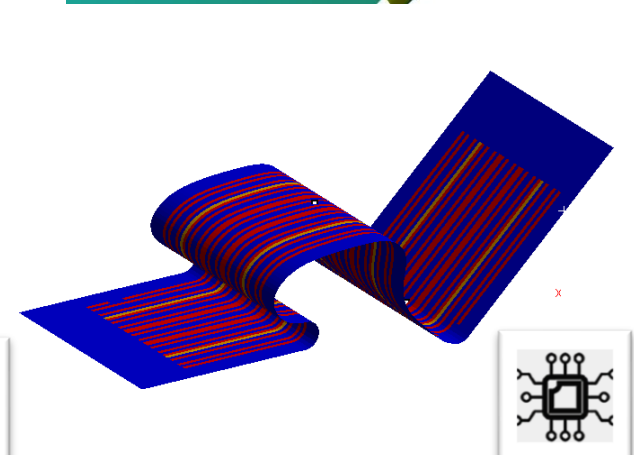
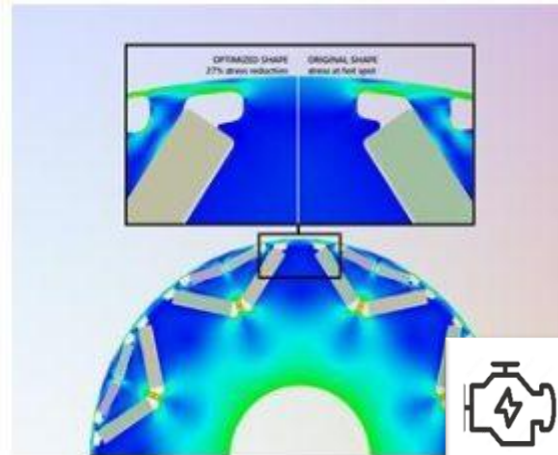
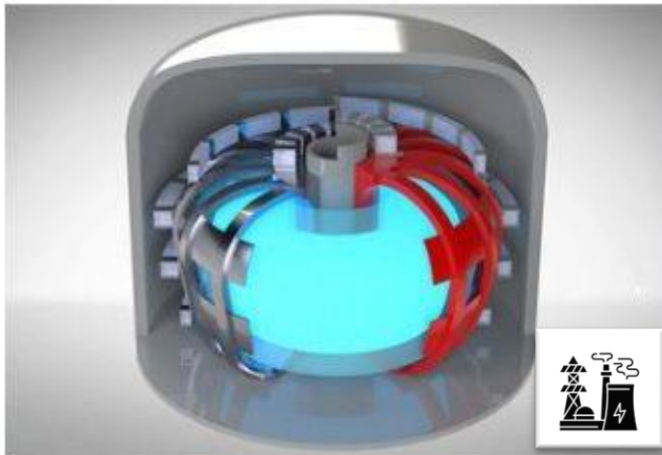
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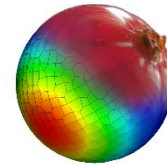
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Radial Basis Functions

Data Science and Geometrical Intelligence

Radial Basis Functions (RBF) in a nutshell

source points

$$s(\mathbf{x}) = \sum_{i=1}^N \gamma_i \cdot \varphi(\|\mathbf{x} - \mathbf{x}_{k_i}\|) + h(\mathbf{x})$$

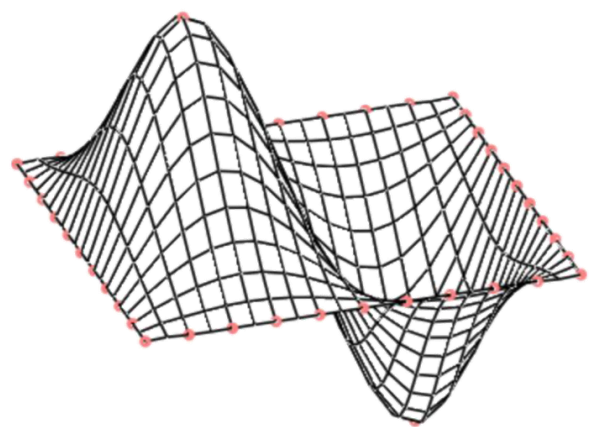
weight

radial basis

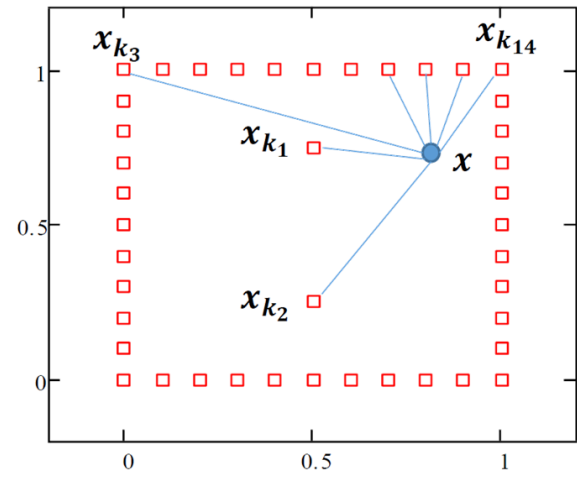
polynomial
e.g. $h(x) = \beta_1 + \beta_2x + \beta_3y + \beta_4z$

shift of the target point to the i-th data site

| RBF | $\varphi(r)$ |
|---------------------|---------------------------------------|
| Spline type (Rn) | $r^n, n \text{ odd}$ |
| Thin plate spline | $r^n \log(r) \text{ } n \text{ even}$ |
| Multiquadratic (MQ) | $\sqrt{1 + r^2}$ |

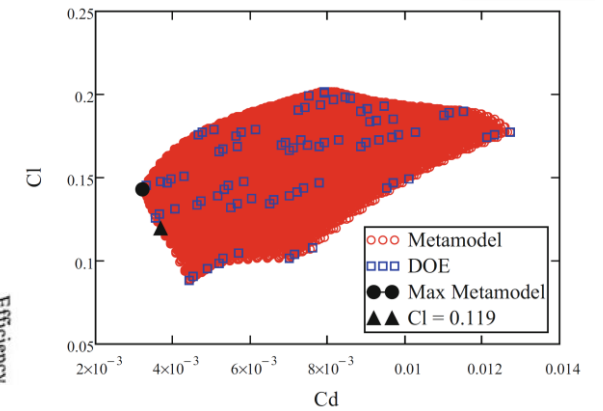
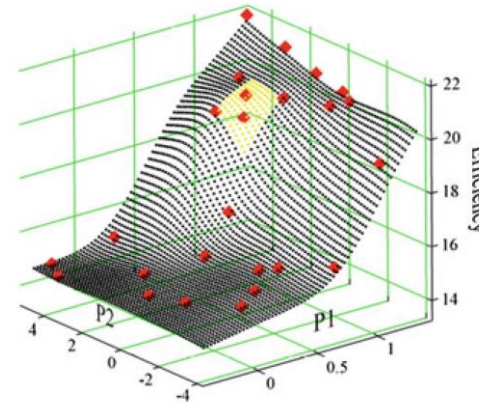


RBF are a very powerful mathematical tool able to interpolate **everywhere** in the \mathbb{R}^n space a function given at scattered **source points**



Interpolators in multi-dimensional spaces

- **Data science** problems
 - Inference $\mathbb{R}^n \Rightarrow \mathbb{R}^m$
 - Gaussian RBF is recognized as the “RBF neural network”
 - Useful for **surrogates** in **optimisation**
- 3D space manipulation (shape deformation, data mapping)
 - Field manipulation is a key enabler for **geometric intelligence**
 - Mapping is a key enabler for multi-physics and as a “morphing extender”



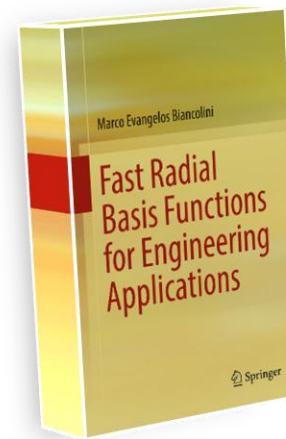
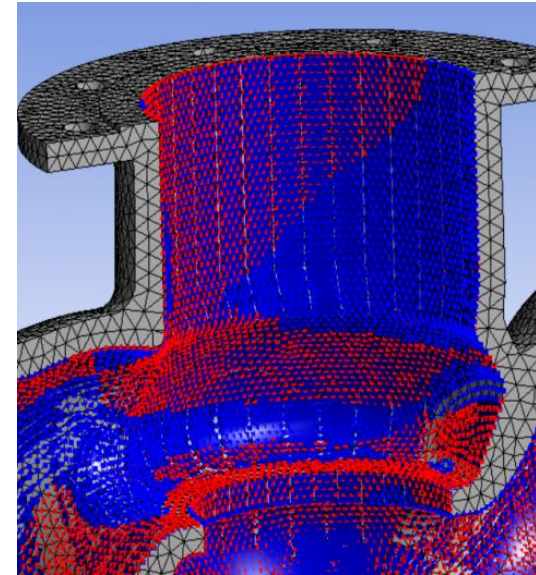


Shape Optimisation

Parameter-based and Parameter-free Workflows

RBF Mesh Morphing

- We adopt **Radial Basis Functions** (RBF) to drive mesh morphing (smoothing) from a list of source points and their displacements
 - Surface shape changes
 - Volume mesh smoothing
- RBF are recognized to be one of the **best mathematical tool** for mesh morphing

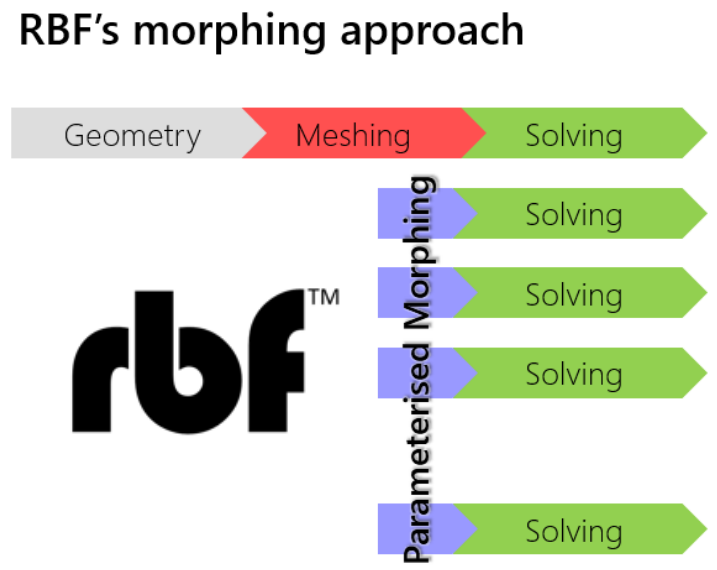
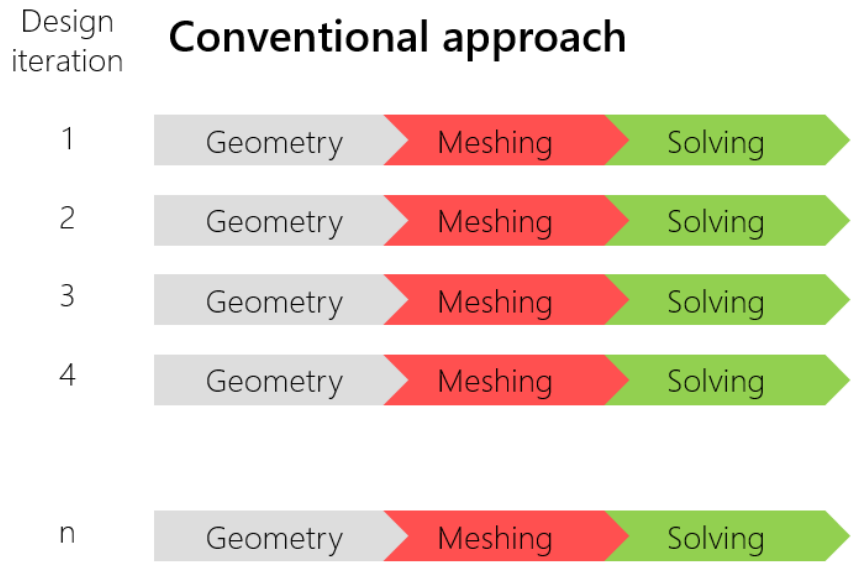


$$\begin{cases} s_x(\mathbf{x}) = \sum_{i=1}^N \gamma_i^x \varphi(\|\mathbf{x} - \mathbf{x}_{s_i}\|) \\ s_y(\mathbf{x}) = \sum_{i=1}^N \gamma_i^y \varphi(\|\mathbf{x} - \mathbf{x}_{s_i}\|) \\ s_z(\mathbf{x}) = \sum_{i=1}^N \gamma_i^z \varphi(\|\mathbf{x} - \mathbf{x}_{s_i}\|) \end{cases}$$



Parameter-based Shape Optimisation

- Morphing is a **key enabler** for optimisation and Digital Twins
- The turnaround time of the optimization is usually **reduced by a factor five** (weeks becomes days)

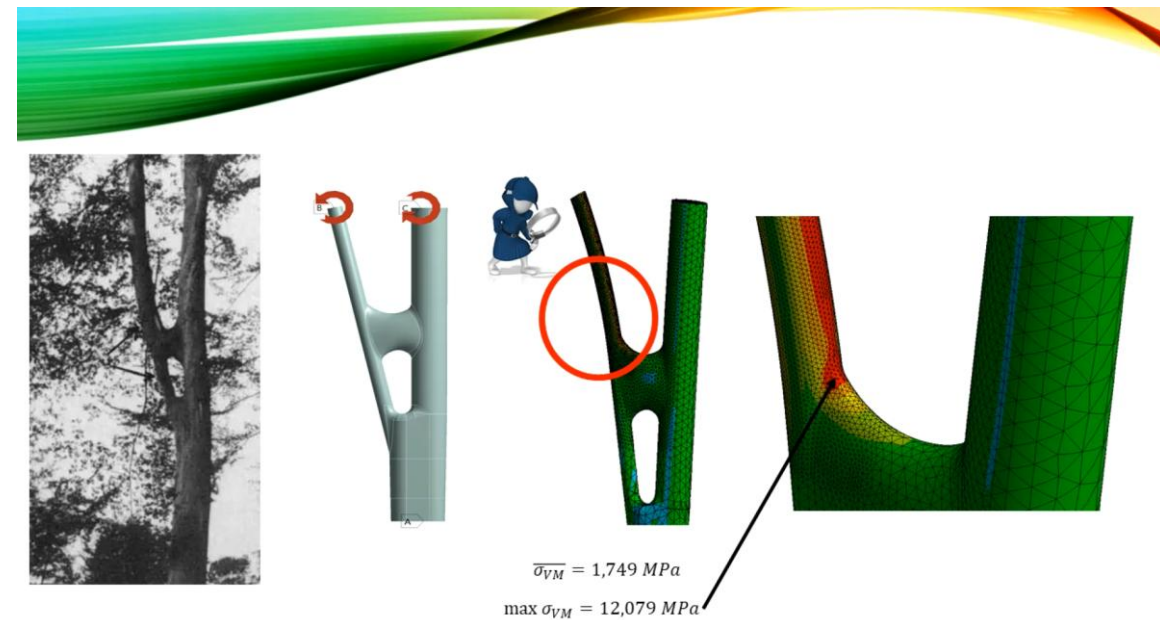
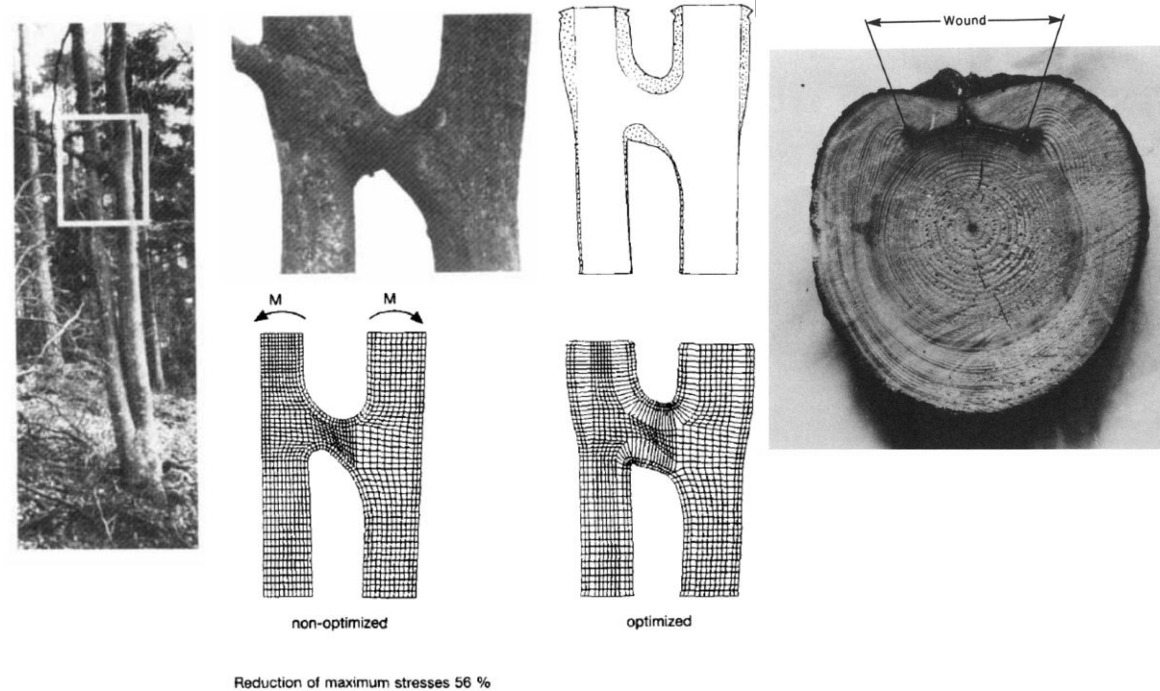


Parameter-free Shape Optimisation

- The **BGM** (biological growth method) approach is based on the observation that **biological** structures growth is driven by **local level of stress**.
- Bones and trees' trunks are able to **adapt the shape** to mitigate the stress level due to external loads.
- The process is driven by stress **value at surfaces**. Material can be **added or removed** according to local values.

$$\dot{\epsilon} = k(\sigma_{Mises} - \sigma_{ref})$$

- Was originally proposed by Mattheck & Burkhardt in 1990





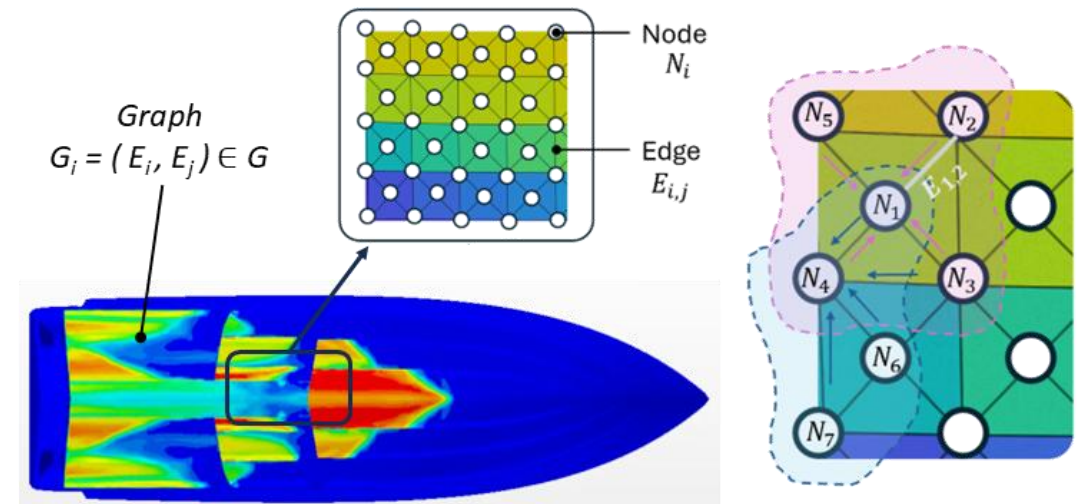
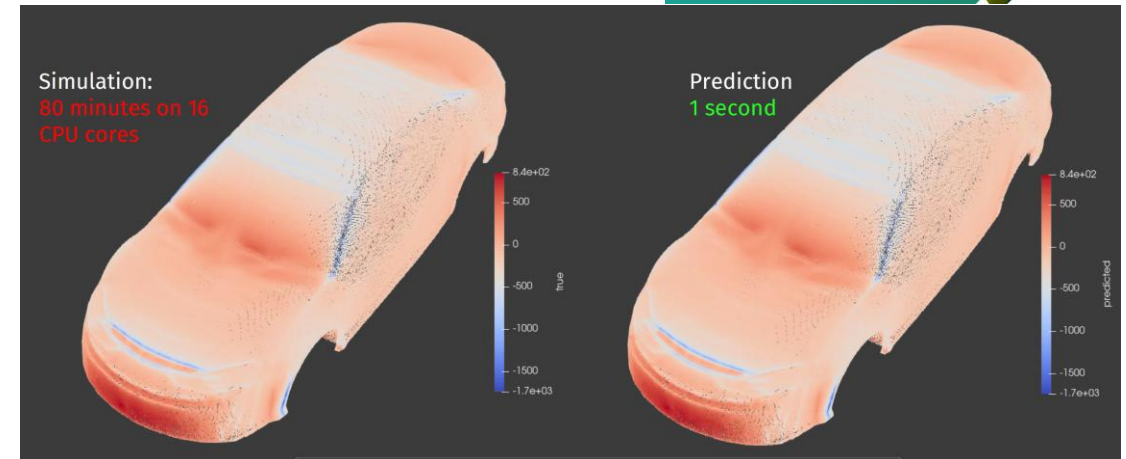
Digital Engineering

Real Time Interactive CAE Models

Digital Engineering Applications

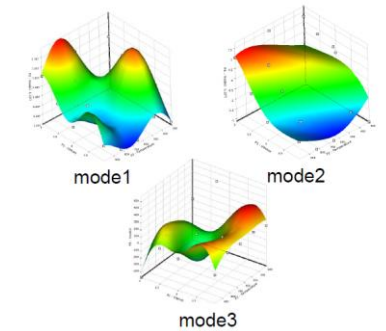
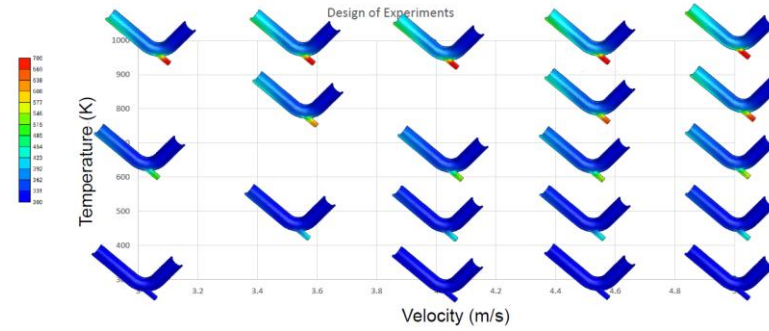


- **Digital Twin** – digital replica of asset useful at design and operation
- CAE adoption is evolving: single verification, design variations, automated optimisation, **parametric space exploration** (snapshots)
- **Machine learning** is the reference for AI based approach
- High/medium fidelity simulations allow to generate the training data: **synthetic datasets**



Interactive Digital Twins

- **Reduced Order Models (ROM)** are compressed (POD) ready to be inferred (RBF)
- Functional Mock-Up Units (**FMU**) make the models portable
- Unity rendering
 - Meta Quest 3 AR/VR
 - Apple VisionPro?

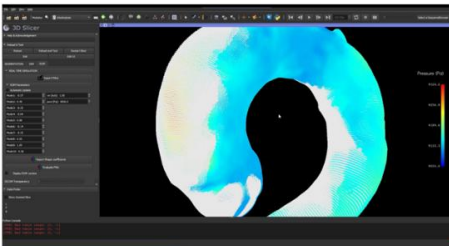
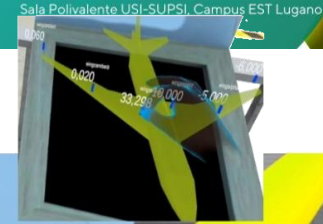
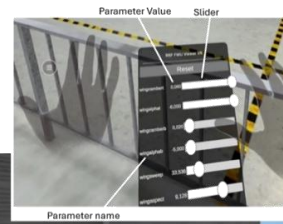
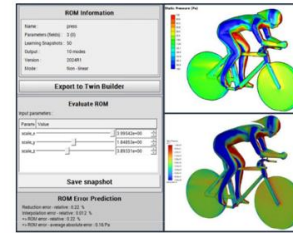
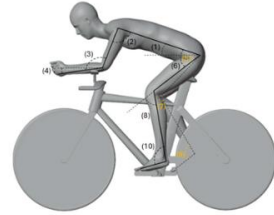
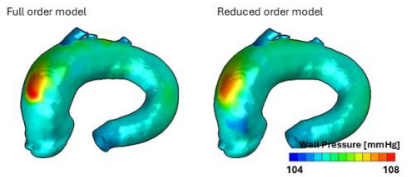
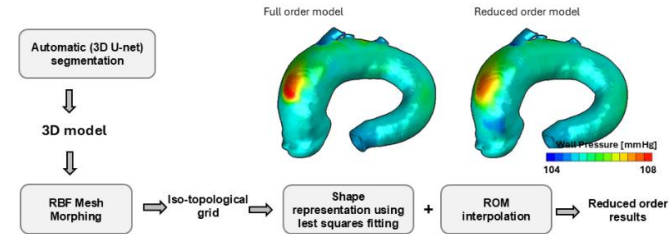
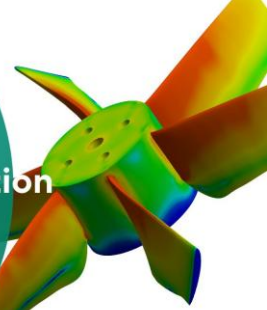


POD+RBF = ROM

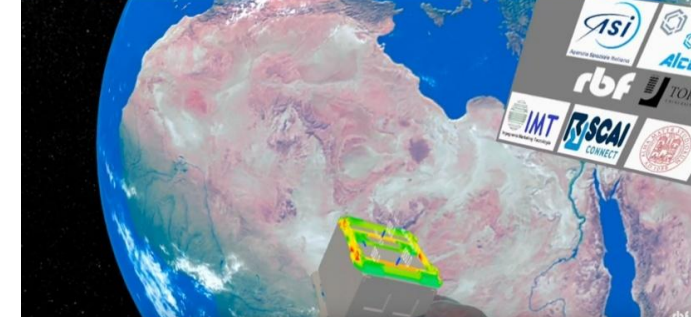
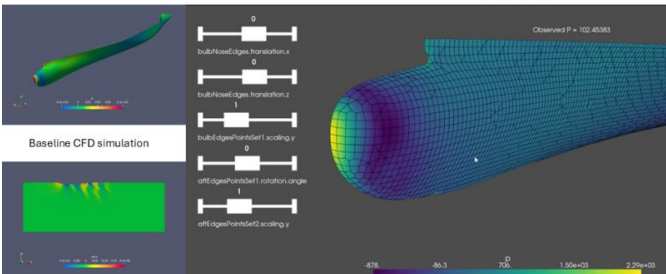
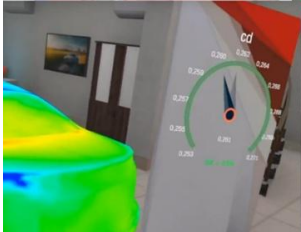
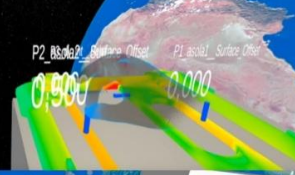
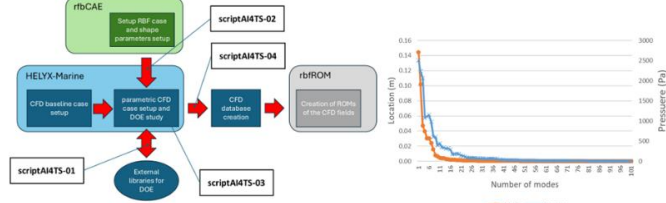
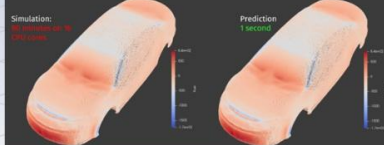
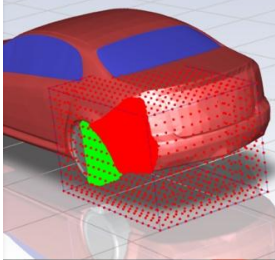
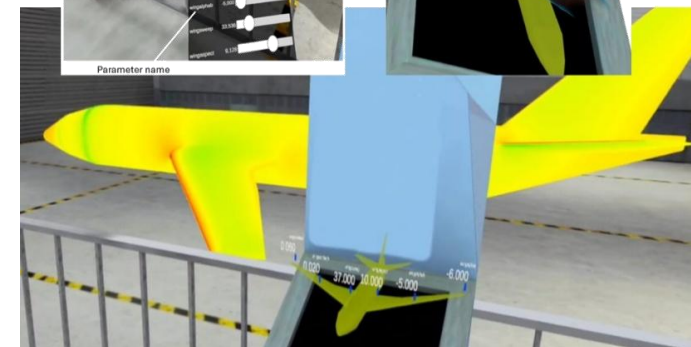
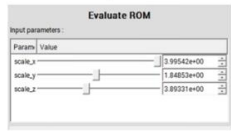
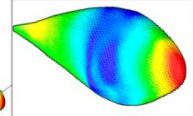
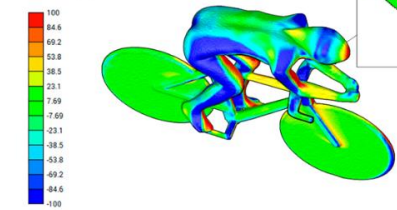
$$\text{ROM} = c_1 \times \text{Mode 1} + c_2 \times \text{Mode 2} + c_3 \times \text{Mode 3}$$



Digital Engineering Examples



Static Pressure (Pa)





Two Detailed Industrial Examples

Dallara Formula Car - Vespa Engine

The need for speed...



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Lap time reduction of a race car by a better flow penetration



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Extended durability of an internal combustion engine

...requires limitless performances ...



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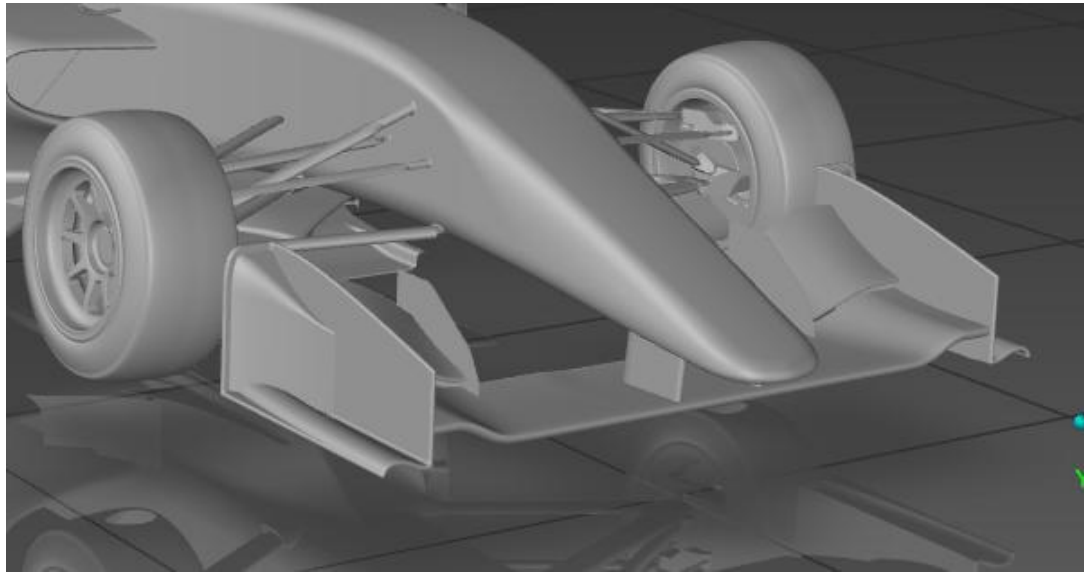
Lap time reduction of a race car by
a better flow penetration



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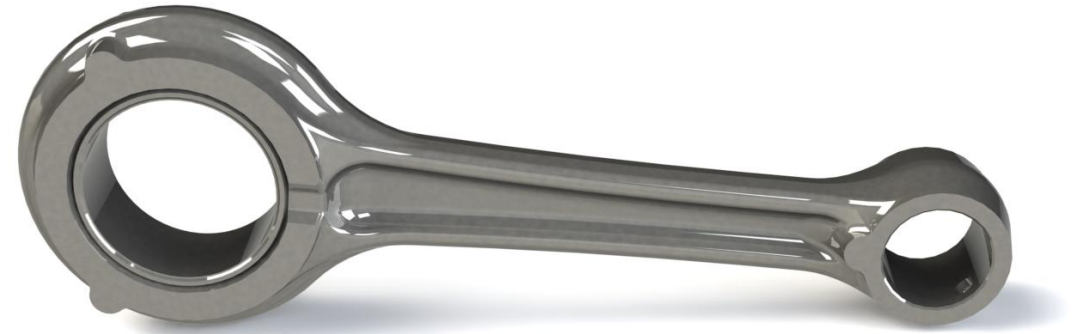
Extended durability of an internal
combustion engine

...to be achieved by acting on KPIs...



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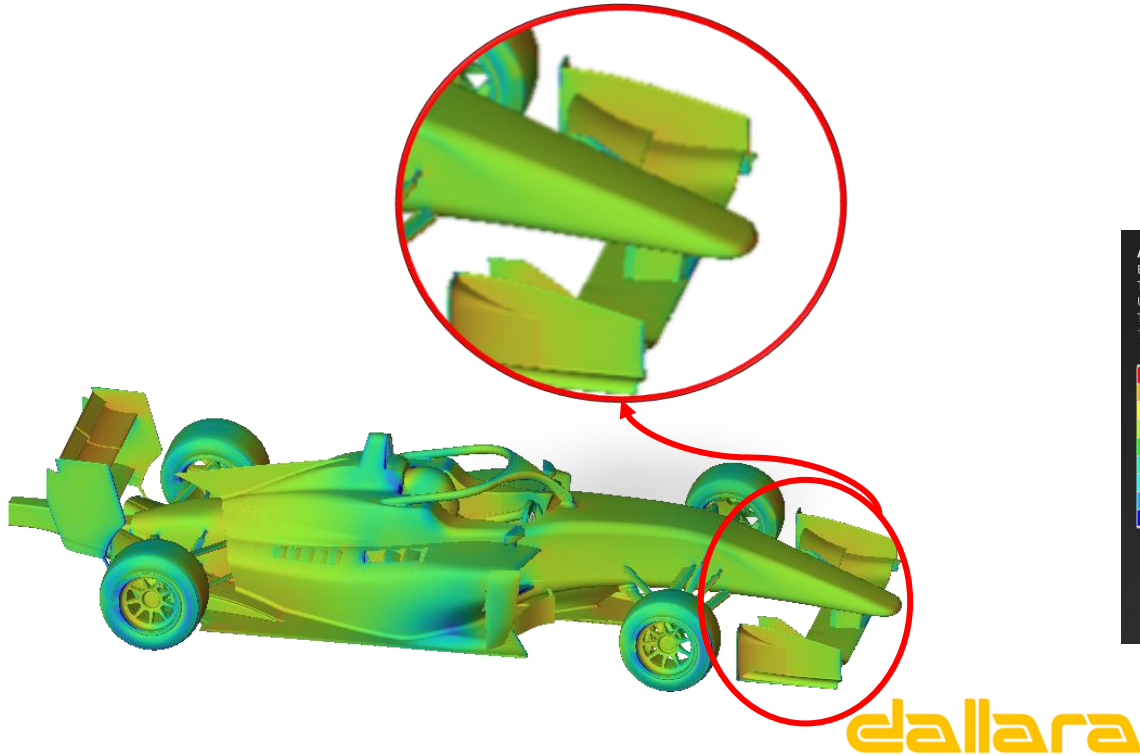
Tweak the design of the front wing
to gain 0.15 drag counts



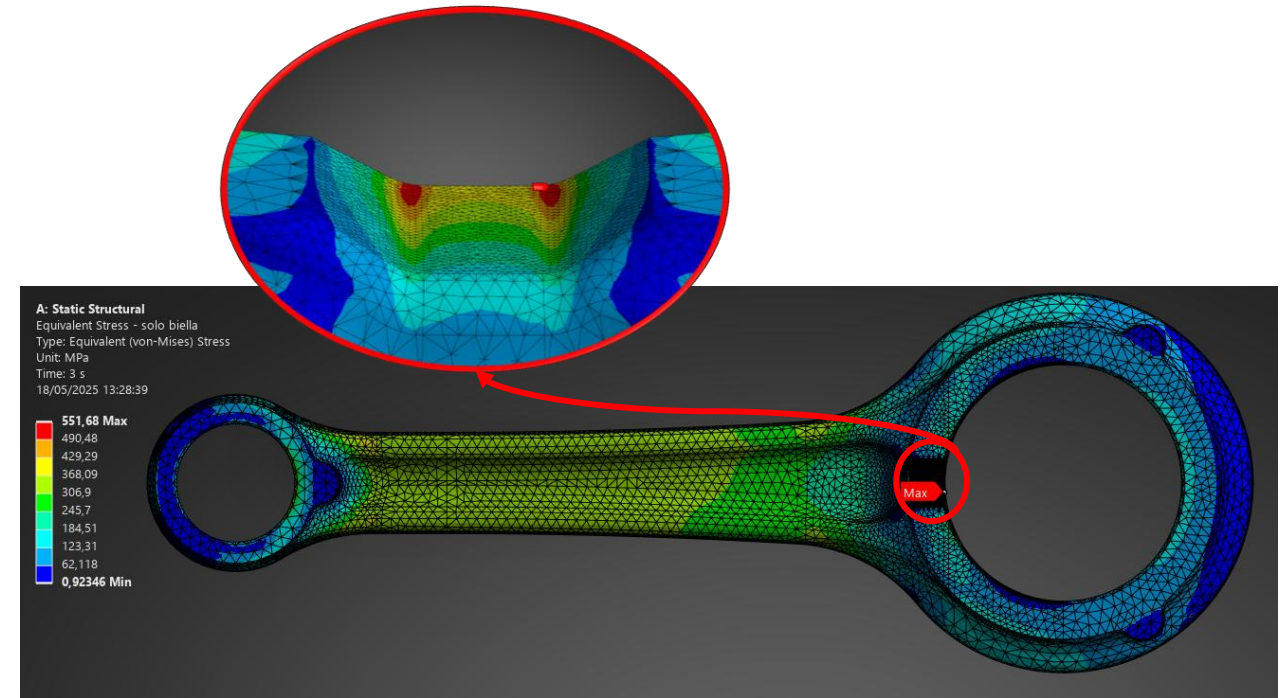
 **PIAGGIO**

Reduce connecting rod stress by
15% to increase its fatigue life

...precisely predicted by CAE simulation.



Fluent CFD provides best in class solution for external aero



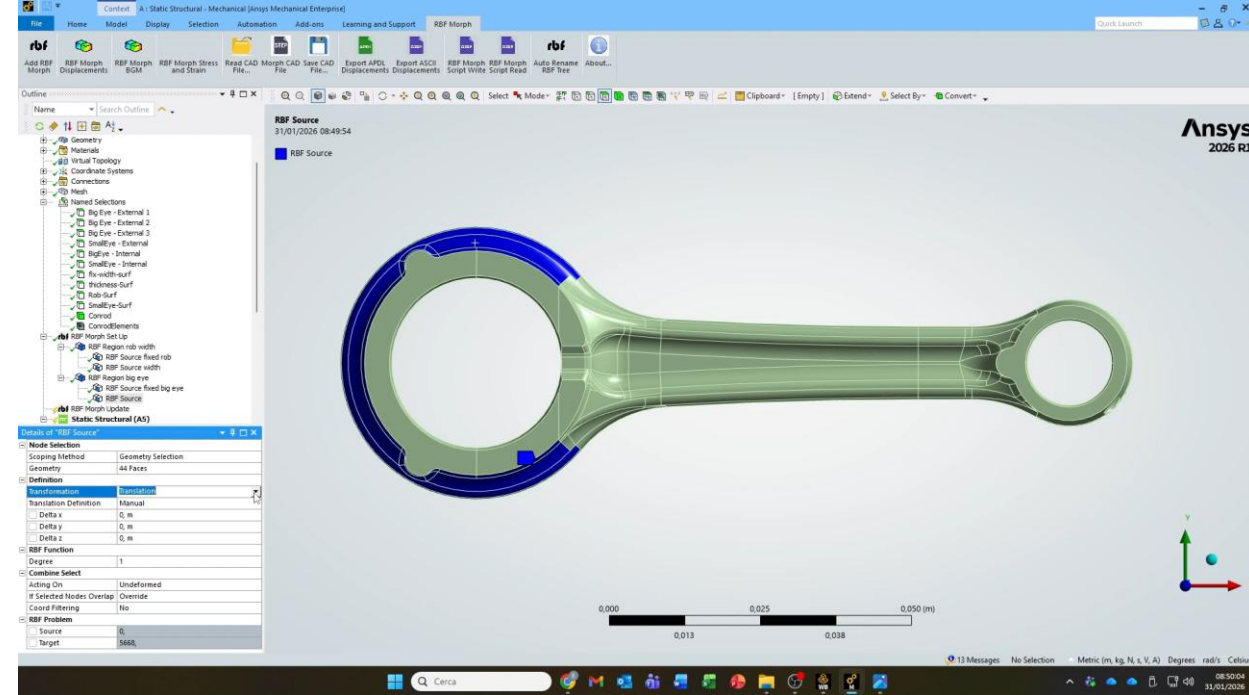
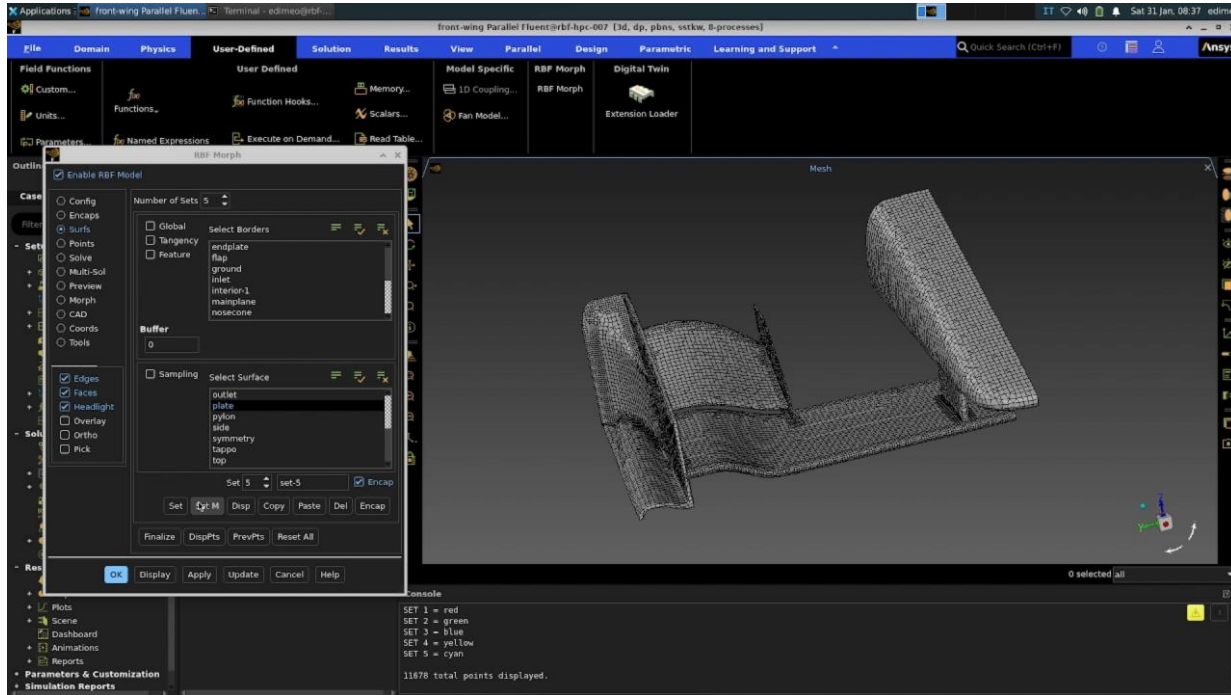
Mechanical FEA is the industry standard for stress prediction



Parameter-based Shape Optimisation

We need Shape Intelligence to identify new designs

Step #1: define the RBF shape parameters

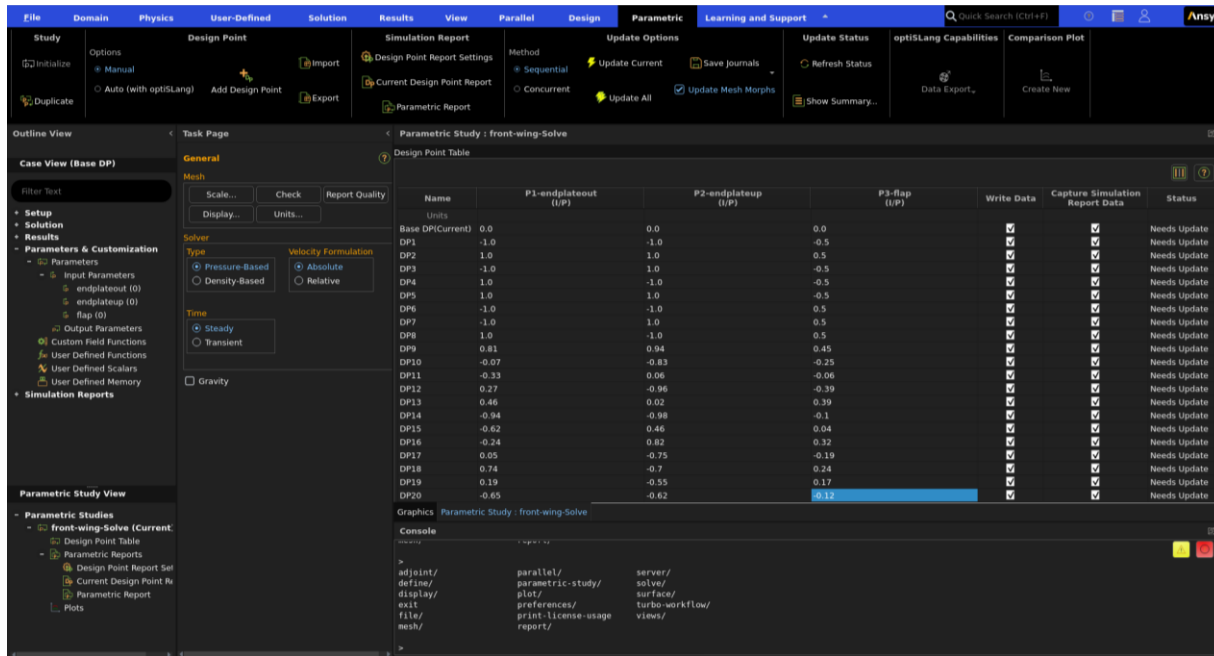


Shape parameters are defined interacting with Fluent GUI and TUI



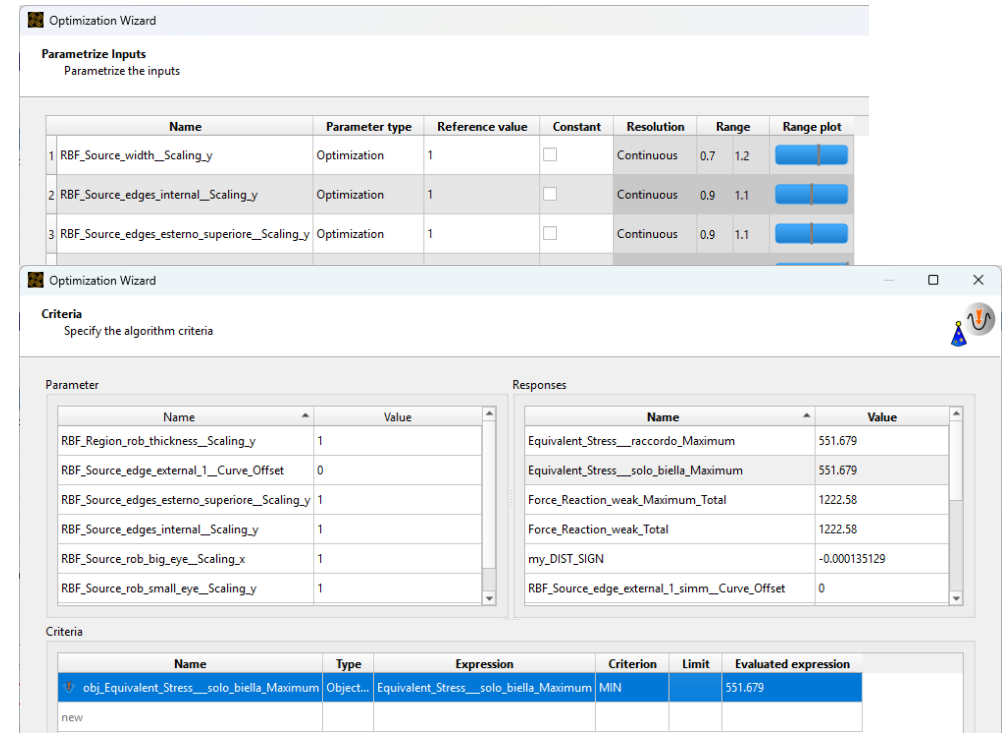
Shape parameters are defined in the morphing tree inside Mechanical

Step #2: automate design exploration



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The Fluent optimisation is steered by optiSLang stand alone

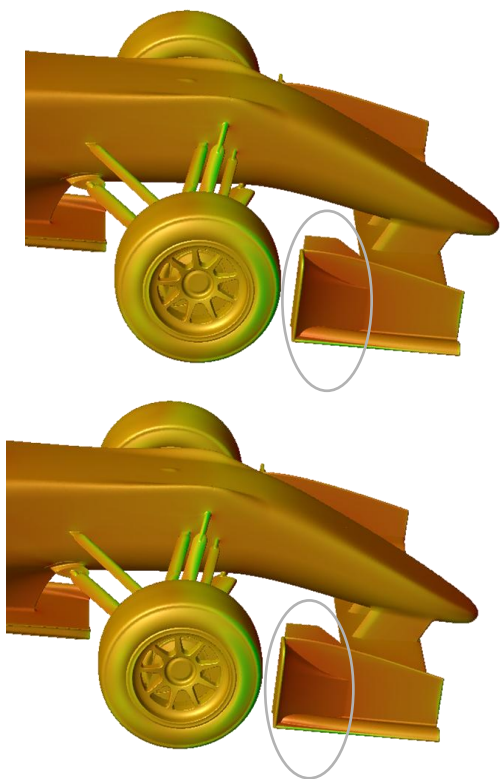


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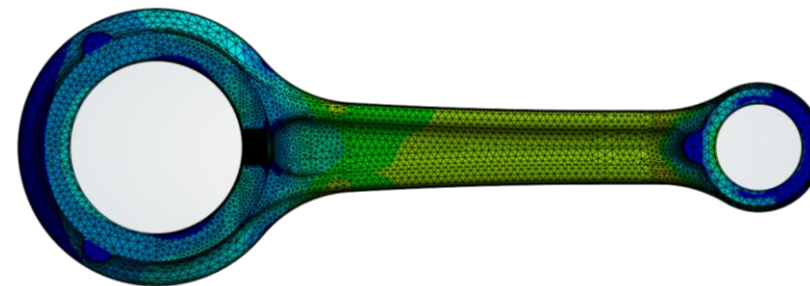
The Mechanical optimisation is steered by optiSLang within Workbench

Step #3: validate the results

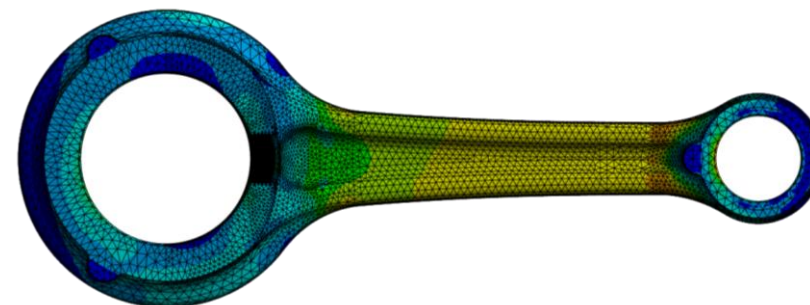
-0.19 drag points gain



Baseline Design



Optimised Design



-17.4% Hotspot Stress reduction

| Front Wing | P1 | P2 | P3 | Cd |
|------------|-------|------|------|--------|
| Baseline | 1 | 1 | 1 | 0.4333 |
| Optimised | -0.81 | 0.93 | 0.45 | 0.4247 |



| Conrod | P1 | P2 | P3 | P4 | P5 | P6 | P7 | σ_{VM} [MPa] |
|-----------|------|------|--------|-------|-------|-------|-------|---------------------|
| Baseline | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 551 |
| Optimised | 1.23 | 0.78 | -0.087 | 1.102 | 0.781 | 0.995 | 0.954 | 455 |



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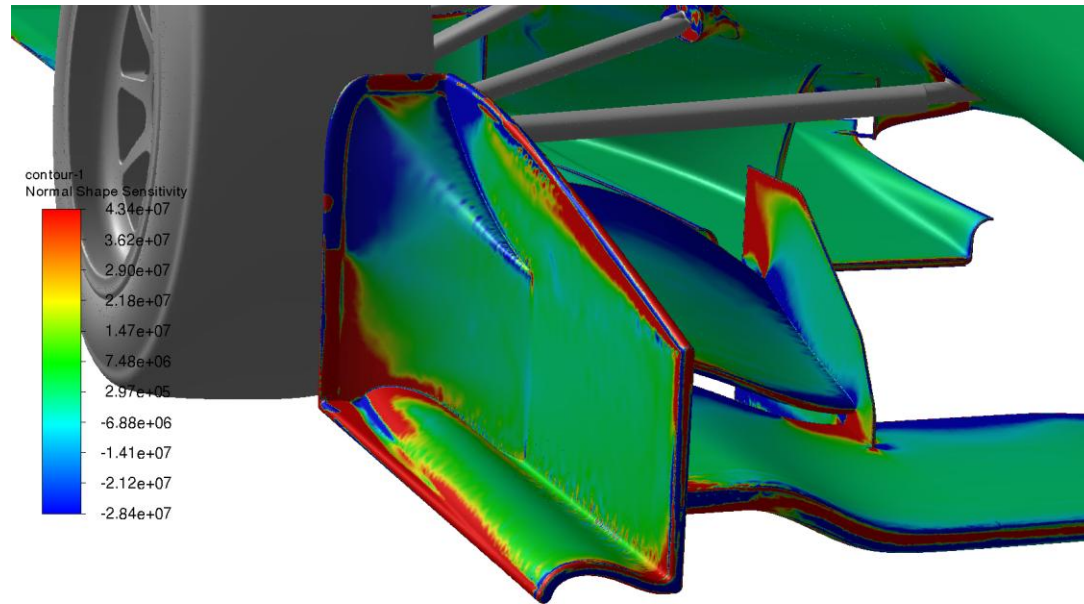


Parameter-free Shape Optimisation

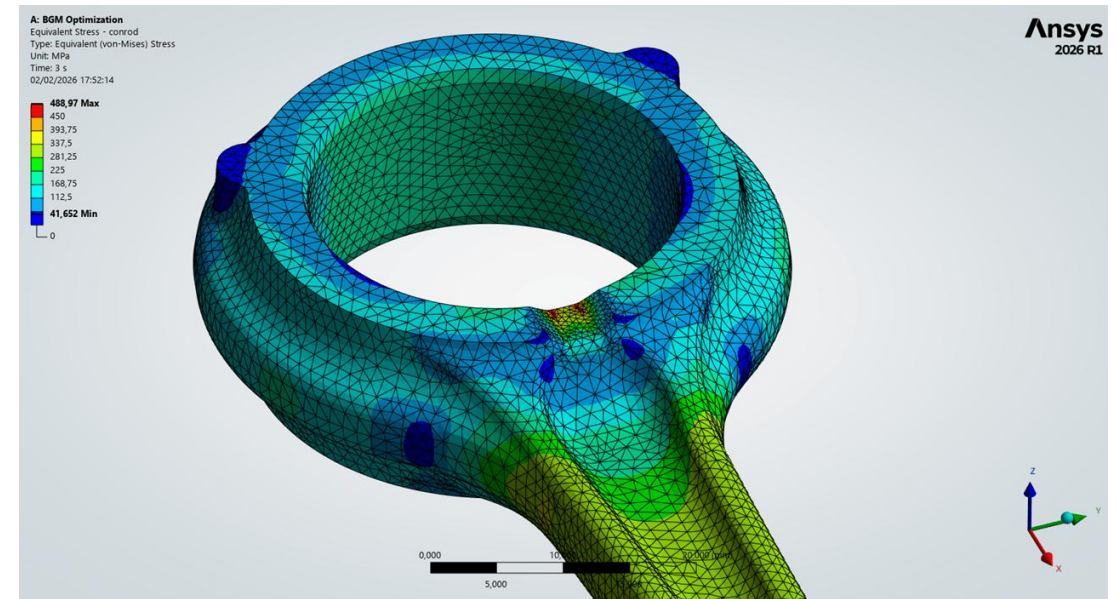
The standard optimisation workflow allows to reach the KPI targets.

Can we refine it more?

Step #4: switch to parameter-free



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RBF Morph Fluids offers a strong integration with the **adjoint solver**. **Surface are sculpted** whilst geometrical constraints are respected.

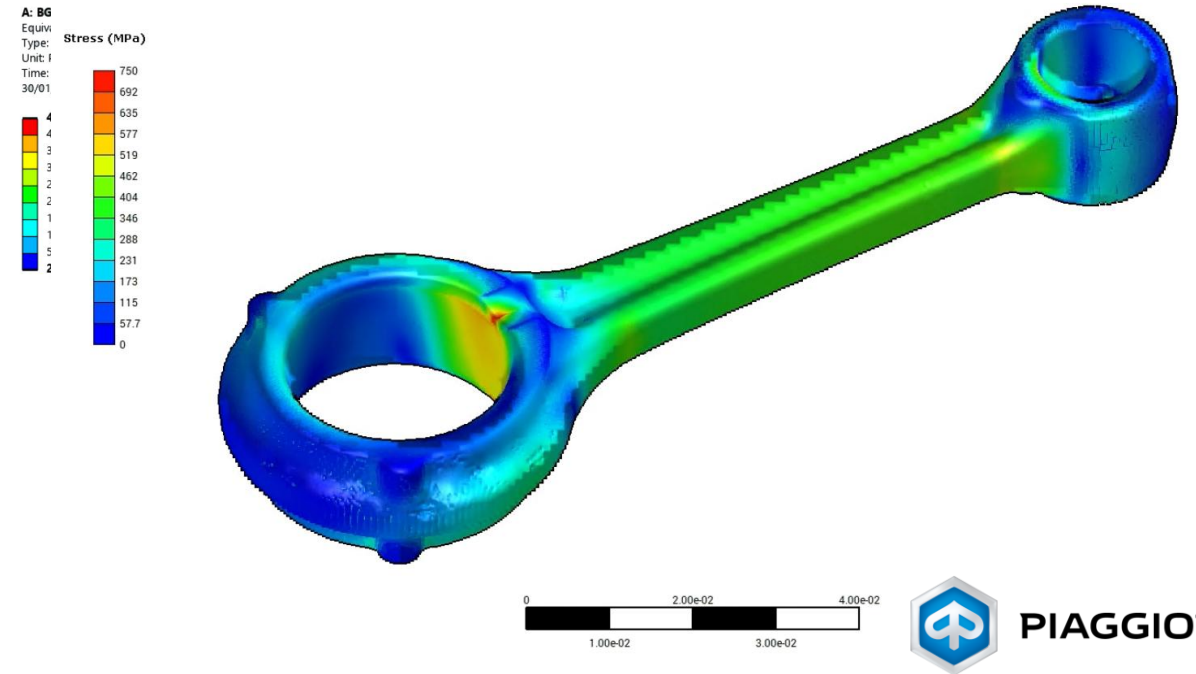
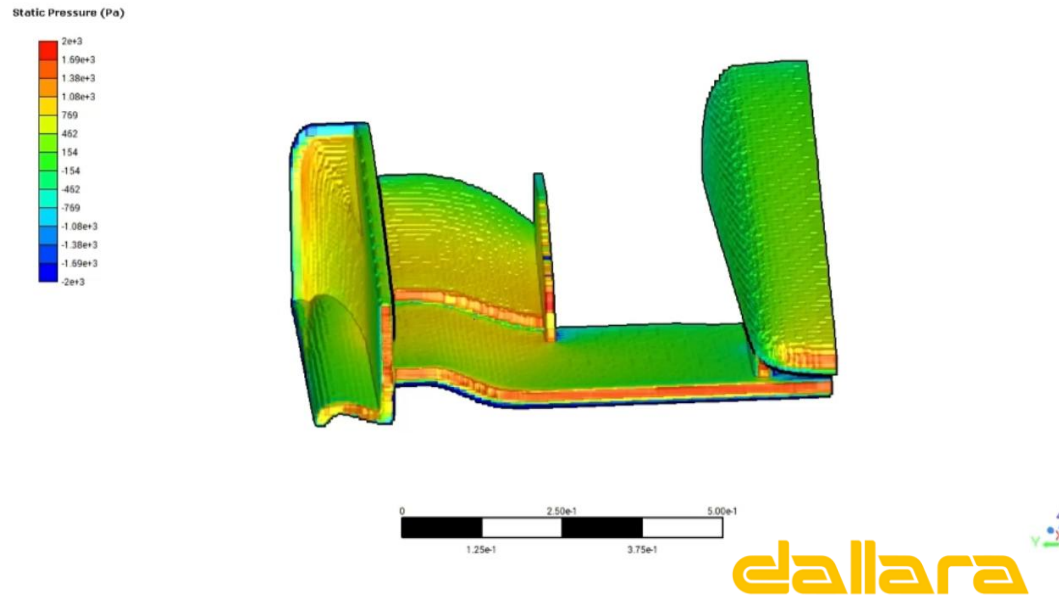
The BGM (**biological growth method**) allows to reduce the stress. **Manufacturing constraints** are easily applied.



Interactive Shape Optimisation

The automated refinement works well but we want manual control.
Can we enable an interactive AI assisted approach?

Step #5: interactive ROM with Twin Builder

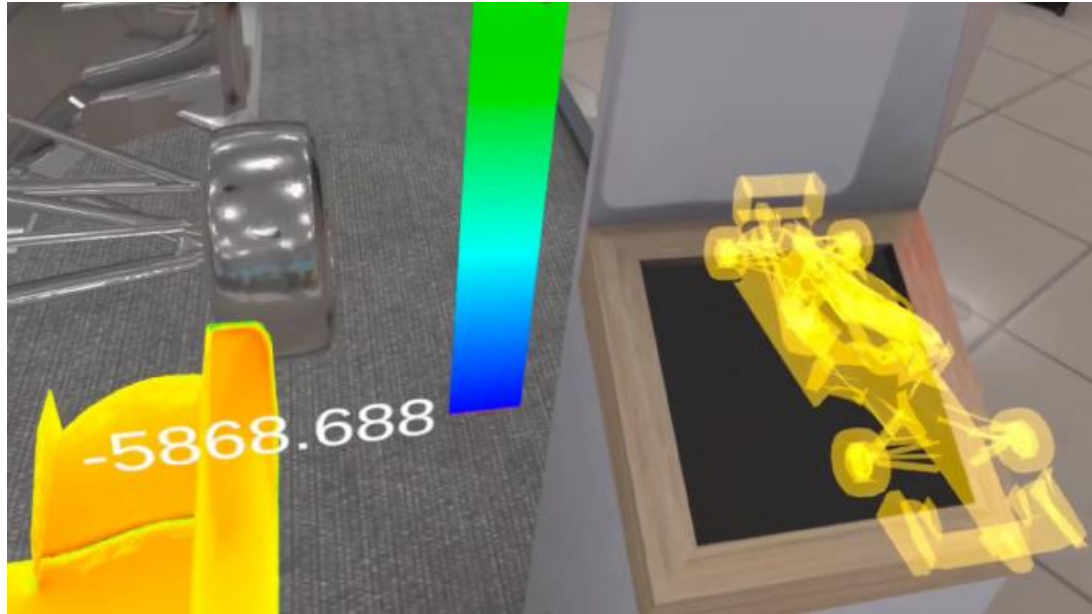


RBF Morph Fluids quickly creates **snapshots** to train the AI based ROM of Twin Builder by feeding the standard and the GPU solver of Fluent.

The parametric FEA model allows the automated creation of snapshots to train the **AI based ROM** of **Twin Builder**.

Step #6: the ROM is published as a VR experience

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The functional mock-up units generated by Twin Builder can be imported in rbfVR Publisher and deployed in rbfVR Player.

Are you willing to improve further the design?

Have a try and wear the VR device!



Conclusions

- Radial Basis Functions help **Digital Engineering** by providing **geometric intelligence** and an effective **inference** tool
- Parameter-free and parameter-based shape optimisation is possible
- Two industrial examples, Formula 3 car aero drag reduction and fatigue optimisation of a connecting rod of a **scooter engine**, have been demonstrated
- Roadmaps toward an **AI based approach** were presented
- Interactive VR implementation has been shown
- Next Steps?

Next steps? Aeronautical

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Revolutionizing aerodynamic design with a VR-enabled workflow

by Andrea Lopez¹, Marco Camponeschi², Marco E. Biancolini^{1,2}
1. University of Rome Tor Vergata - 2. RBF Morph

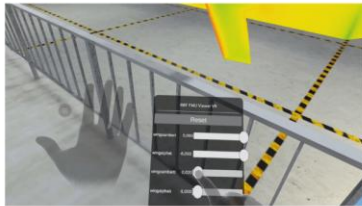
The aerospace industry is undergoing a rapid digital transformation, embracing innovative technologies to streamline design workflows, increase efficiency, and drive innovation like never before. One of the most exciting breakthroughs is the integration of virtual reality (VR) with reduced order models (ROMs), to enable real-time aerodynamic design exploration.

Bridging the gap: from CAD to VR
Aerodynamic performance optimization has traditionally been a highly iterative process. Engineers must analyse multiple design variants using high-fidelity CFD simulations, which are accurate but computationally expensive and time-consuming. Integrating

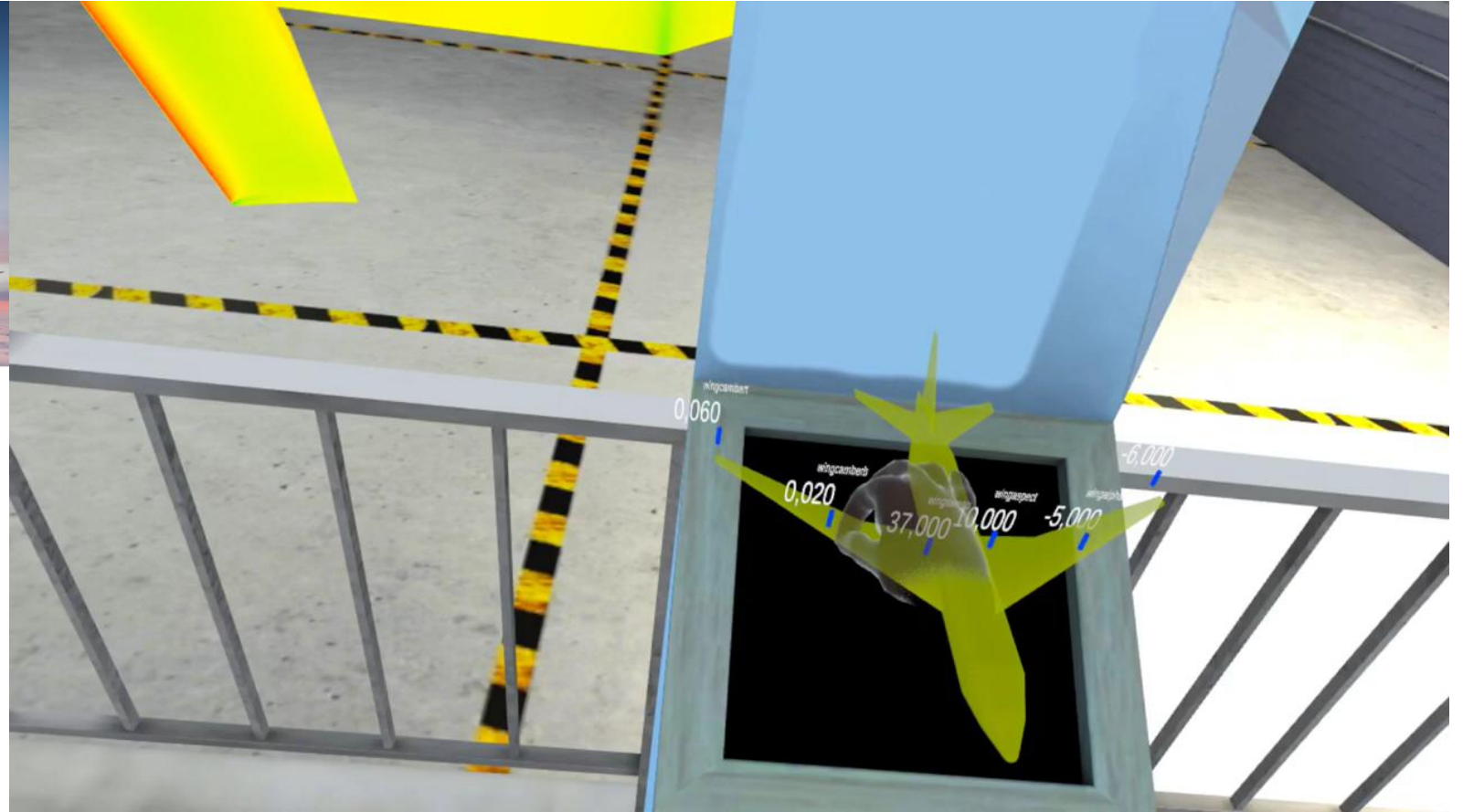
VR and ROMs into the workflow helps overcome these challenges by providing a real-time design environment with interactive parameter exploration.

By incorporating CAD parameterization and mesh morphing, engineers can seamlessly

Traditionally, engineering workflows have been slow and resource-intensive, with design iterations relying on lengthy computational fluid dynamics (CFD) simulations. This article presents a game-changing approach – one that seamlessly links CAD modelling, CFD, and ROMs within an interactive VR dashboard. The result? A fast, immersive, and intuitive tool that allows engineers to explore designs in real-time, making the whole process more dynamic and efficient.



12 Futuribles - Spring 2025



Next steps? Space

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Proceeding Paper

The Payload Design of the CUBesat Solar Polarimeter (CUSP), for Space Weather and Solar Flares X-Ray Polarimetry

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Abstract: The CUBesat Solar Polarimeter (CUSP) project is a CubeSat mission orbiting the Earth aimed to measure the linear polarization of solar flares in the hard X-ray band by means of a Compton scattering polarimeter. CUSP is a project in the framework of the Alcor Program of the Italian Space Agency aimed to develop new CubeSat missions. It is approved for a Phase B study. In this work we describe some design solutions adopted for the most important design drivers of the payload. In particular, we report on the payload preliminary multi-physical design, including an orbital thermal environment preliminary assessment and a implementation of the static/dynamic finite element analysis. Moreover, a method for topology optimization of relevant components is discussed.

Keywords: CUSP; space weather; solar flare; mechanical design; multi-physical analysis; payload



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Next steps? Healthcare



Article

The Hemodynamic Effect of Modified Blalock–Taussig Shunt Morphologies: A Computational Analysis Based on Reduced Order Modeling

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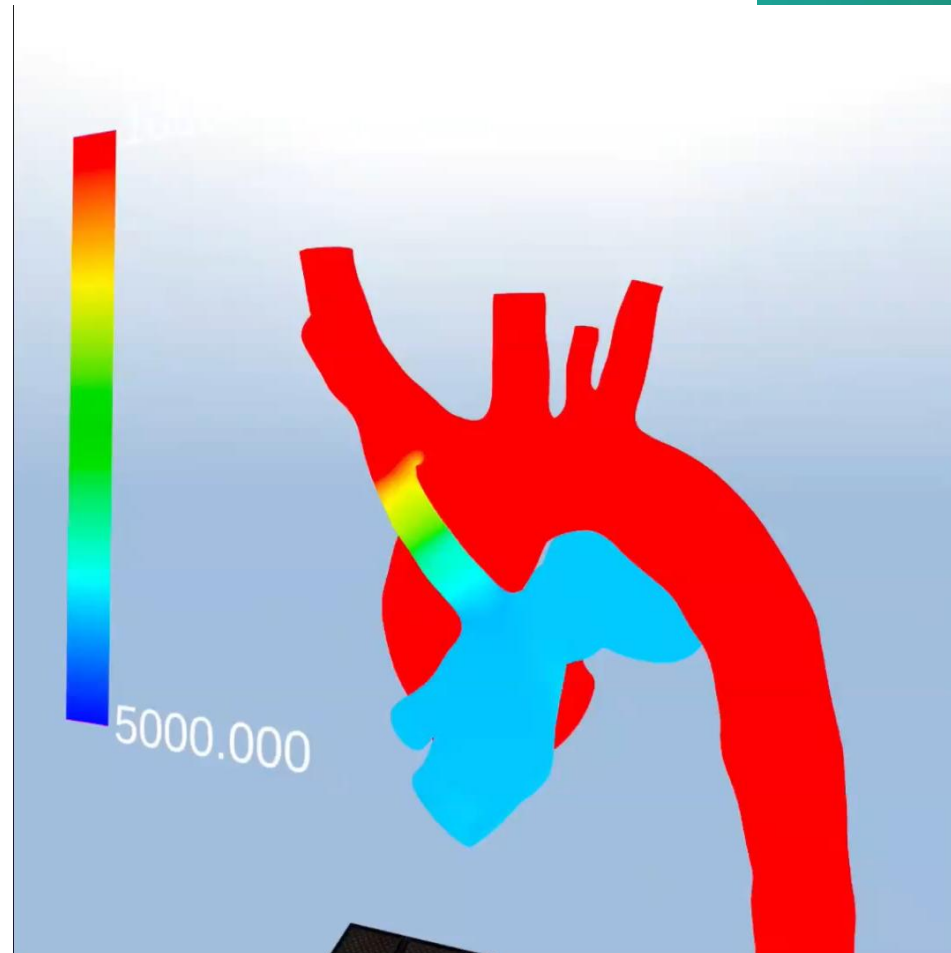
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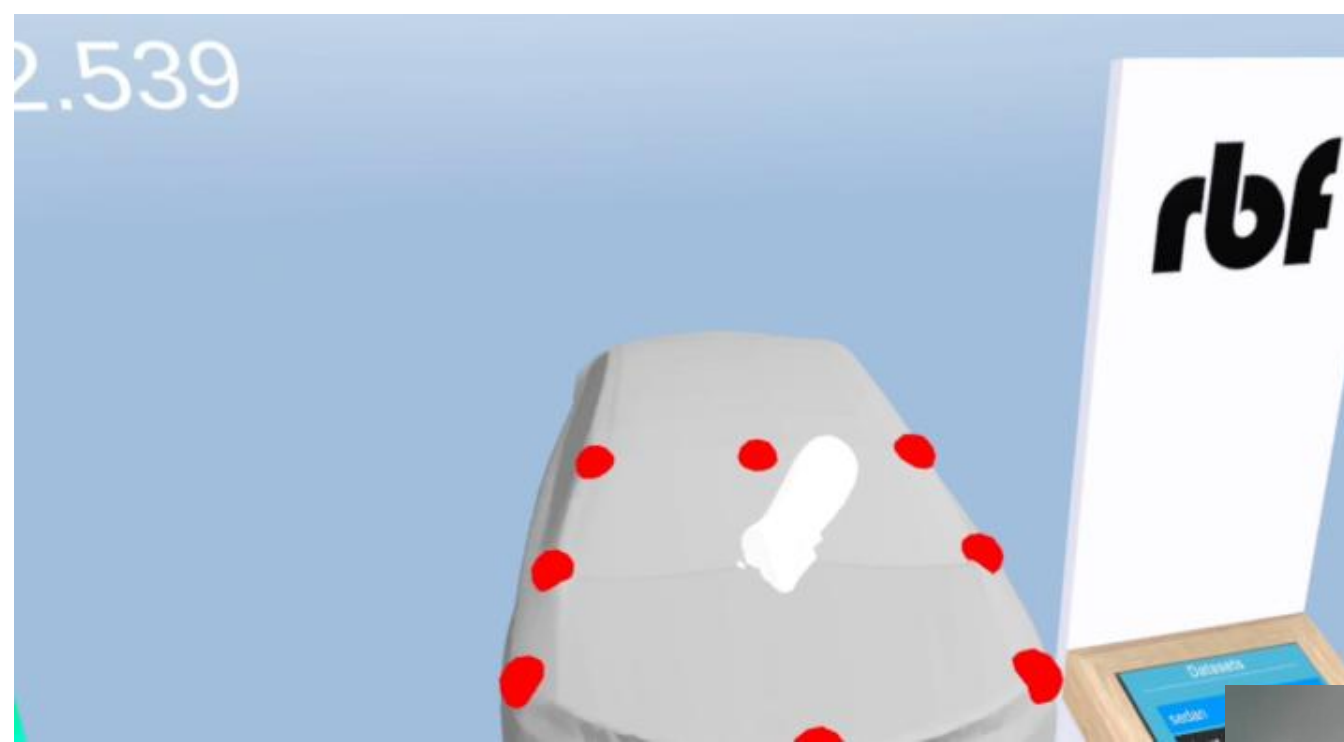
Abstract: The Modified Blalock–Taussig Shunt (MBTS) is one of the most common palliative operations in case of cyanotic heart diseases. Thus far, the decision on the position, size, and geometry of the implant relies on clinicians' experience. In this paper, a Medical Digital Twin pipeline based on reduced order modeling is presented for fast and interactive evaluation of the hemodynamic parameters of MBTS. An infant case affected by complete pulmonary atresia was selected for this study. A three-dimensional digital model of the infant's MBTS morphology was generated. A wide spectrum of MBTS geometries was explored by introducing twelve Radial Basis Function mesh modifiers. The combination of these modifiers allowed for analysis of various MBTS shapes. The final results proved the potential of the proposed approach for the investigation of significant hemodynamic features such as velocity, pressure, and wall shear stress as a function of the shunt's morphology in real-time. In particular, it was demonstrated that the modifications of the MBTS morphology had a profound effect on the hemodynamic indices. The adoption of reduced models turned out to be a promising path to follow for MBTS numerical evaluation, with the potential to support patient-specific preoperative planning.

Keywords: computational fluid dynamics; reduced order modeling; hemodynamics; Modified Blalock–Taussig Shunt; RBF mesh morphing; Medical Digital Twin

1. Introduction

Congenital heart defects are currently present in about 9 of every 1000 live-born children [1,2]. Several of these pathologies, such as pulmonary atresia and Tetralogy of Fallot, are linked with cyanotic heart diseases in which low levels of oxygen in the blood are encountered. Especially in the case of the pulmonary atresia, the pulmonary valve plane is absent, leading to full blockage of the blood flow towards the lungs. Among the most diffused approaches to tackle these complications, the modified Blalock–Taussig shunt (MBTS) is a surgical procedure which consists of implanting a synthetic shunt between the subclavian and pulmonary artery. The MBTS is frequently adopted for the treatment of newborn children suffering from pulmonary hypoperfusion triggered by congenital heart diseases [3]. In this way, sufficient levels of oxygenated blood are delivered to the





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Many thanks for your attention!

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