

Real-Time Medical Digital Twins: Geometry, Simulation, and Immersive Interaction

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RBF Morph Company founder Associate Professor

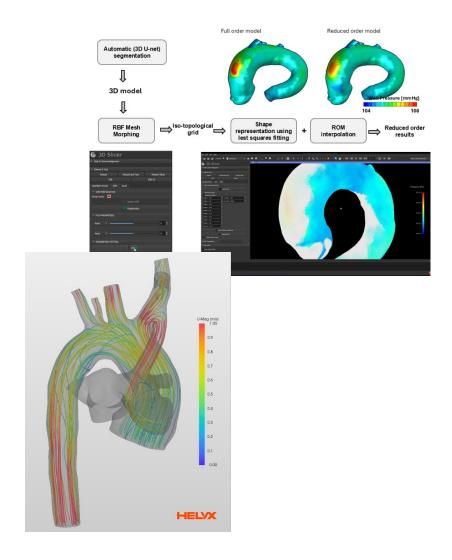






Agenda

- Digital Twins
- Radial Basis Functions
- Reduced order models
- Shape generation
- Interactive Real-Time Design Exploration
- Medical Digital Twins
 - o Interactive Medical Digital Twins in 3d Slicer
 - o Support to shunting procedures
- RBF Morph technologies
- Conclusions







Digital Twins

Digital Engineering Applications

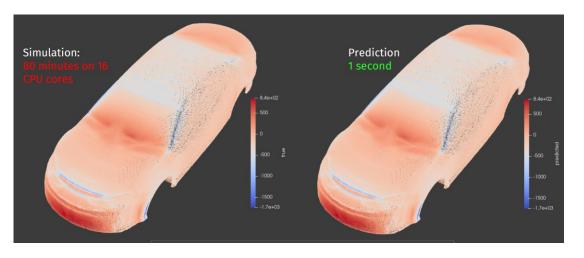


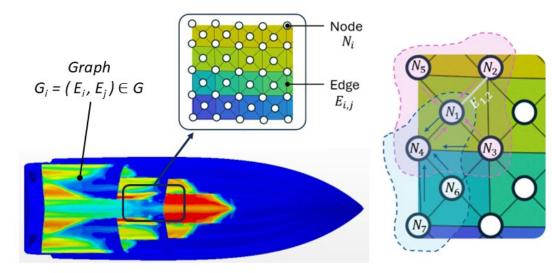




- **Digital Twin** digital replica of asset useful at design and operation
- CAE adoption is evolving: single verification, design variations, automated optimisation, parametric space exploration (snapshots)
- Machine learning is the reference for «Al» based approach
- High/medium fidelity simulations allow to generate the training data: synthetic datasets











Radial Basis Functions

Data Science and Geometrical Intelligence





The evolution of RBF since their inception



- Hardy RL (1971) Multiquadric equations of topography and other irregular surfaces. J Geophys Res 76(8):1905–1915
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 ISSN 1019-7168
- Babuška I, Melenk JM (1997) The partition of unity method. Int J Numer Meth Eng 40(4):727–758, https://doi.org/10.1002/(SICI)1097-0207(19970228)40:4:727::AID-NME86:3.0.CO;2-N
- Beatson RK, Greengard L (1997) A short course on fast multipole methods. In: Ainsworth M,Levesley J, Light WA. Marletta M (eds) Wavelets, multilevel methods and elliptic PDEs, Oxford University Press, pp 1–37
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- Carr JC, Beatson R, Cherri J, Mitchell T, Fright W, McCallum B (2001) Reconstruction and representation of 3D objects with radial basis functions. In: Proceedings
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- Faul AC, Goodsell G, Powell MJD (2005) A Krylov subspace algorithm for multiquadric interpolation in many dimensions. IMA J Numer Anal 25:1–24
- · Botsch M, Kobbelt L (2005) Real-time shape editing using radial basis functions. In: Marks J, Alexa M (eds) Computer graphics, 24(3), Eurographics
- Beatson RK, Powell MJD, Tan AM (2007) Fast evaluation of polyharmonic splines in three dimensions. IMA J Numer Anal 27:427–450. https://doi.org/10.1093/imanum/drl027
- Tobor I, Reuter P, Schlick C (2006) Reconstructing multi-scale variational partition of unity implicit surfaces with attributes. Graph Models 68(1):25–41.
- Jakobsson S, Amoignon O (2007) Mesh deformation using radial basis functions for gradient based aerodynamic shape optimization. Comput Fluids 36(6):1119–1136.
- de Boer A, Van der Schoot MS, Bijl H (2007) Mesh deformation based on radial basis function interpolation. Comput Struct 85(11–14):784–795.
- Rendall TCS, Allen CB (2009) Efficient mesh motion using radial basis functions with data reduction algorithms. J Comput Phys 228(17):6231–6249
- Yokota R, Barba LA (2011) Treecode and fast multipole method for n-body simulation with cuda. GPU Comput Gems Emerald Ed, p 113
- **Biancolini** ME (2012) Mesh morphing and smoothing by means of Radial Basis Functions (RBF): a practical example using Fluent and RBF morph. In: Handbook of research on computational science and engineering: theory and practice, pp 34.
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- Biancolini, M. E. (2017). Fast radial basis functions for engineering applications (pp. 1-36). Cham: Springer International Publishing.

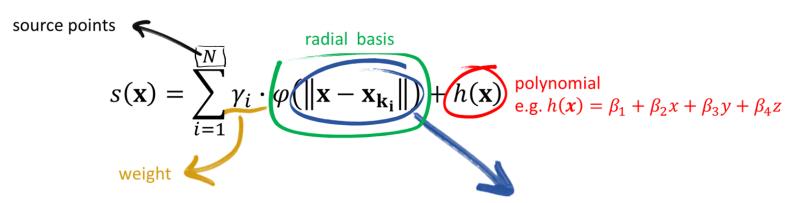
- Hardy Multiquadric
- Greengard Fast Multi Pole
- Powell generalisation to \mathbb{R}^n
- Beatson thin plate spline
- Wendland compact support
- Babuška Partition of Unity
- FGP fast iterative MQ in \mathbb{R}^n
- Jakobsson, de Boer, morphing
- Botsch, interactive morphing
- Biancolini, LCM, first RBF industrial software
- Biancolini, Fast RBF Book

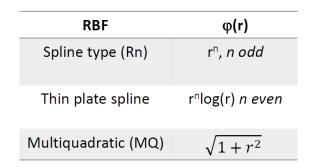




Radial Basis Functions (RBF) in a nutshell

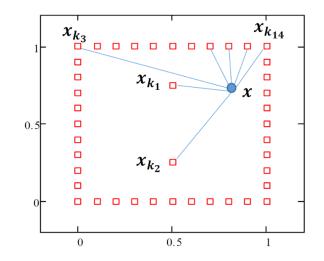


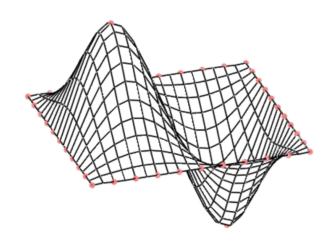




shift of the target point to the i-th data site

RBF are a very powerful mathematical tool able to interpolate **everywhere** in the \mathbb{R}^n space a function given at scattered **source points**



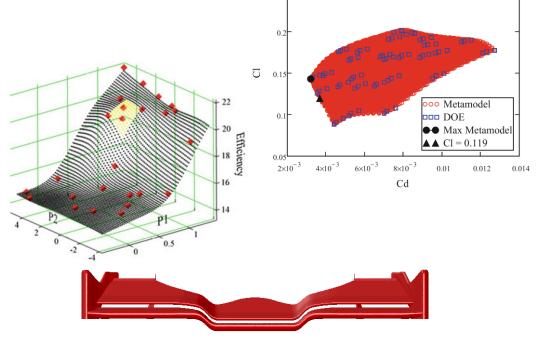




Interpolators in multi-dimensional spaces

- Data science problems
 - \circ Inference $\mathbb{R}^n \Rightarrow \mathbb{R}^m$
 - o Gaussian RBF is recognized as the "RBF neural network"
 - Useful for surrogates in optimization
- 3D space manipulation (shape deformation, data mapping)
 - o Field manipulation is a key enabler for **geometric intelligence**
 - o RBF mapping for multi-physics interfaces and as a "morphing extender"









Reduced order models

Singular Value Decomposition and Principal Orthogonal Decomposition

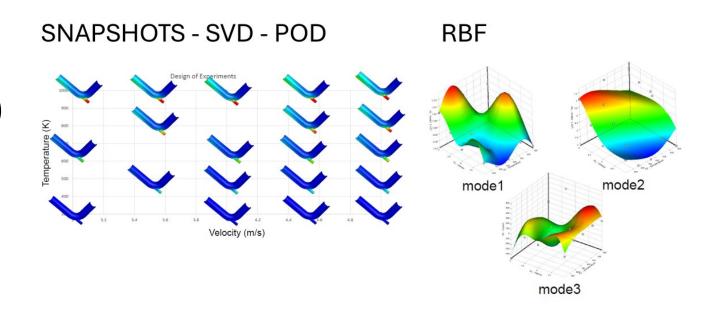


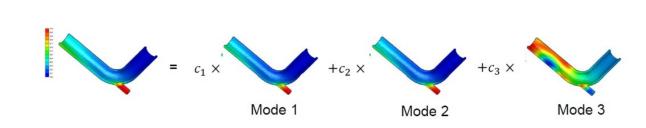


RBF and POD can be combined to get reduced order models (ROM)



- CFD snapshot data are compressed using Singular Value Decomposition (SVD) and Proper Orthogonal Decomposition (POD).
- Al models are trained in the reduced space using Radial Basis Functions (RBFs).
- Full-field solutions are reconstructed via RBF inference and modal expansion.





POD + RBF = ROM



RBF and POD can be combined to get reduced order models (ROM)



Singular Value Decomposition (Beltrami-Jordan 1873)

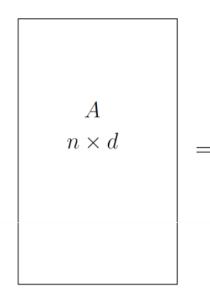
$$X = U \Sigma V^{T}$$

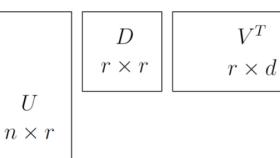
Radial Basis Functions (Hardy 1971)

$$s(\mathbf{x}) = \sum_{i=1}^{N} \gamma_i \, \phi(\|\mathbf{x} - \mathbf{x}_i\|) + p(\mathbf{x})$$

Reconstruction by modal expansion

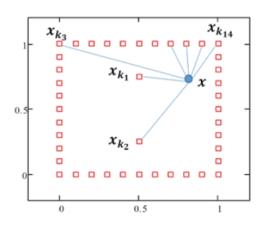
$$A = \sum_{i=1}^{d} \sigma_i \mathbf{u}_i \mathbf{v}_i^T$$

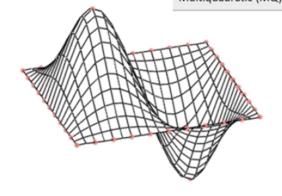




RBF	φ(r)
Spline type (Rn)	r ⁿ , n odd
Thin plate spline	rnlog(r) n even

Multiquadratic (MQ) $\sqrt{1+r^2}$







RBF and POD can be combined to get reduced order models (ROM)



- ROM can be originated by geometrical and physical parameters
 - o ROM of the shape (geometrical modes weights) is trained vs. input parameters
 - o ROM of the CAE solution (**CAE modes weights**) is trained vs. **input** parameters
- ROM can be originated by **multiple parameter-less snapshots** (statistical shape modeling)
 - o ROM of the shape (**geometrical modes weights**) is used to train the ROM of the CAE solution (**CAE modes weights**)
 - o A new shape is projected onto the ROM of the shape and the new CAE solution is inferred





Shape generation

Parameter-based and parameter-free workflows

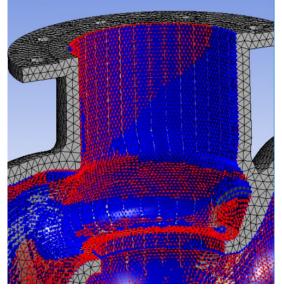






- We adopt Radial Basis
 Functions (RBF) to drive mesh
 morphing (smoothing) from a
 list of source points and their
 displacements
 - o Surface shape changes
 - o Volume mesh smoothing
- RBF are recognized to be one of the **best mathematical tool** for mesh morphing







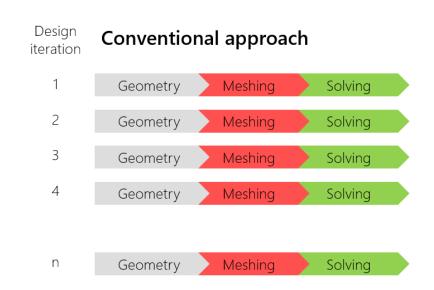
$$\begin{cases} s_{x}(\mathbf{x}) = \sum_{i=1}^{N} \gamma_{i}^{x} \varphi(\|\mathbf{x} - \mathbf{x}_{s_{i}}\|) \\ s_{y}(\mathbf{x}) = \sum_{i=1}^{N} \gamma_{i}^{y} \varphi(\|\mathbf{x} - \mathbf{x}_{s_{i}}\|) \\ s_{z}(\mathbf{x}) = \sum_{i=1}^{N} \gamma_{i}^{z} \varphi(\|\mathbf{x} - \mathbf{x}_{s_{i}}\|) \end{cases}$$



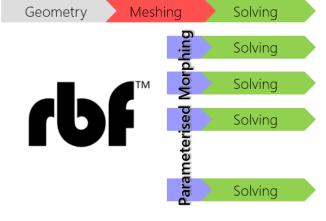


Automated shape generation

- Morphing is a key enabler for Digital Twins
- Multiple snapshots can be generated from shape parameters
- Virtual shapes can be added from SSM
- Synthetic dataset are generated with an high level of **automation**



RBF's morphing approach







Interactive Real-Time Design Exploration

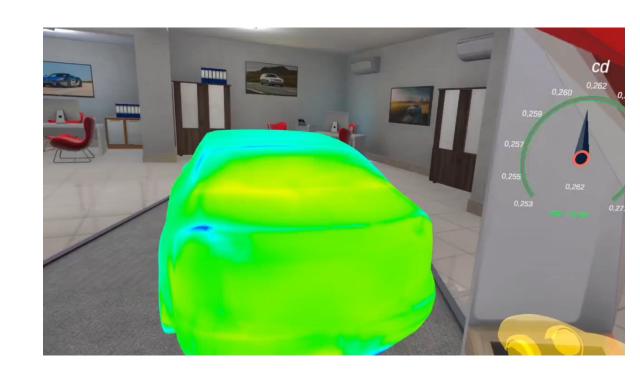
From Advanced Simulation to VR





Interactive Digital Twins?

- High-fidelity simulations big data for training AI models:
 - o Design stage: steer new projects more effectively
 - o Operation stage: **real-time** interactions are key enablers of digital twins
- Challenges:
 - High level of automation required
 - Replicable, easily deployable workflow
- We present a comprehensive solution powered by **Unity rendering** and exported to **Meta Quest 3** AR/VR

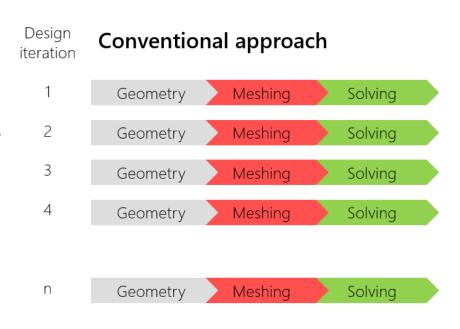




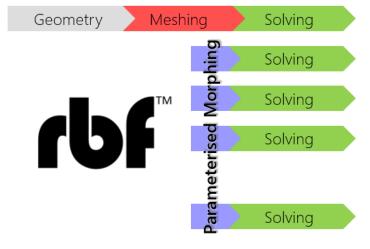
Interactive Digital Twins Challenge #1



- High level of automation to create snapshots is needed
- Geometrical parameters require mesh topology preservation
- RBF mesh morphing combined with CAE solvers



RBF's morphing approach



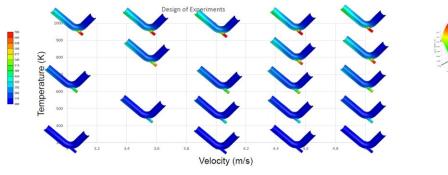


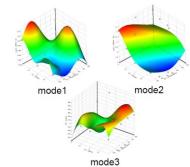
Interactive Digital Twins Challenge #2

Avicenna Alliance
Association for Predictive Medicine

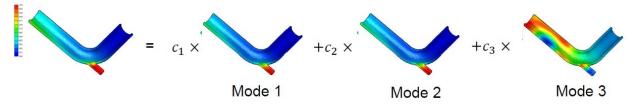
- Replicable, easily deployable workflow?
- Reduced Order Models (ROM) are compressed (POD) ready to be inferred (GARS or RBF)
- Unity rendering
 - o Meta Quest 3 AR/VR
 - o Apple VisionPro?
- Portable Functional Mockup Units







POD+GARS = ROM

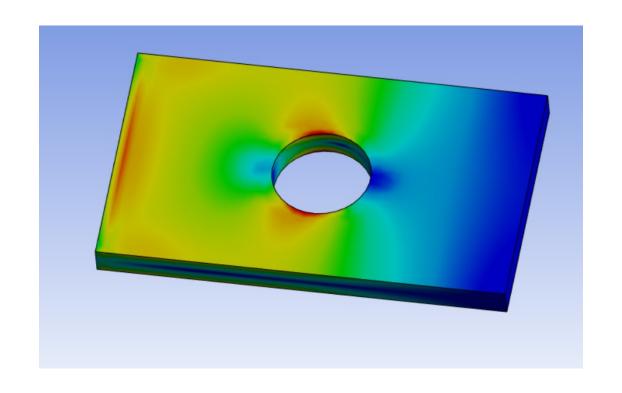




A simple FEA model – ROM - FMU



- Solid model created by CAD
- The notch effect is accurately captured by Mechanical
- RBF morphing allows to create
 one geometrical parameter to
 change the diameter of the hole
- The applied loads is the physical parameter
- Snapshots are exported and the FMU created



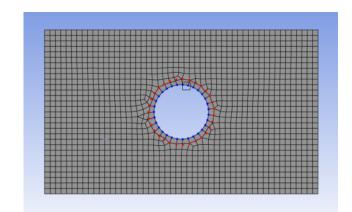




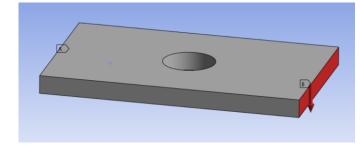
Step 5:

ROM

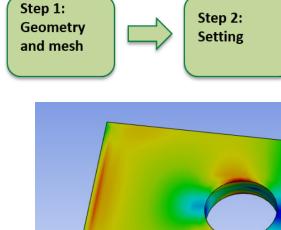
Workflow



Shape parameter: radius offset



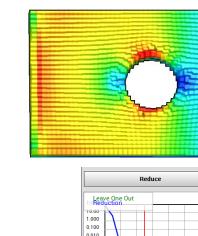
Physical parameter: Force



von Mises stresses

Step 3:

Parameters



Step 4:

DOE: 30 DPs



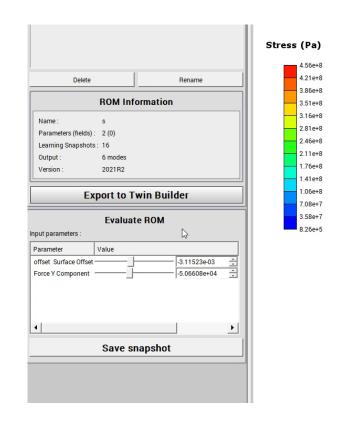
ROM convergence check

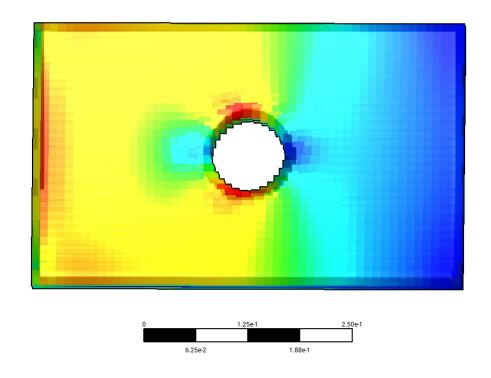




Twin Builder

- ROM Builder
- Input parameters are controlled by the sliders
- Point-based rendering



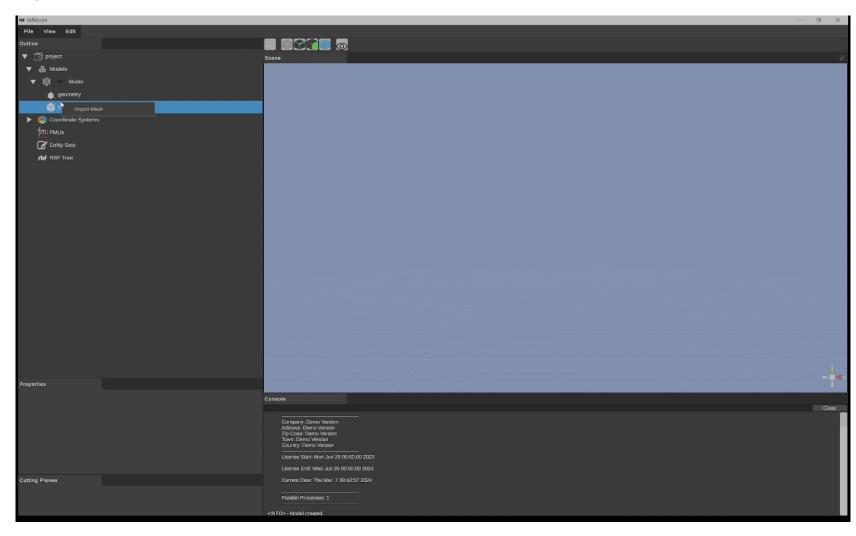






rbfCAE Unity UI

- Unity UI capable to read in surface and FMU
- Input parameters are controlled by handles (json descriptor)
- Surface-based rendering

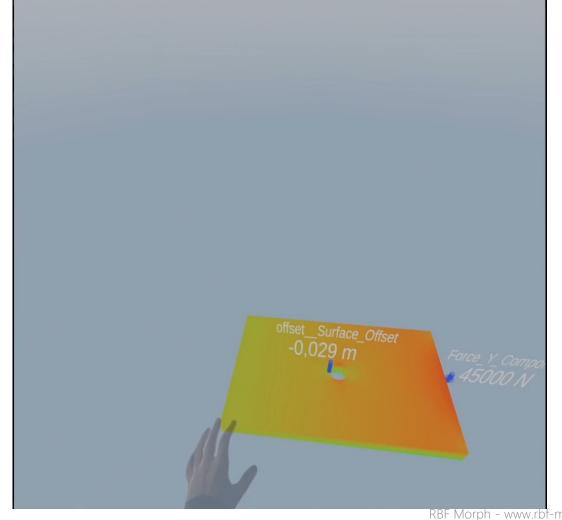






RBF Morph exported VR

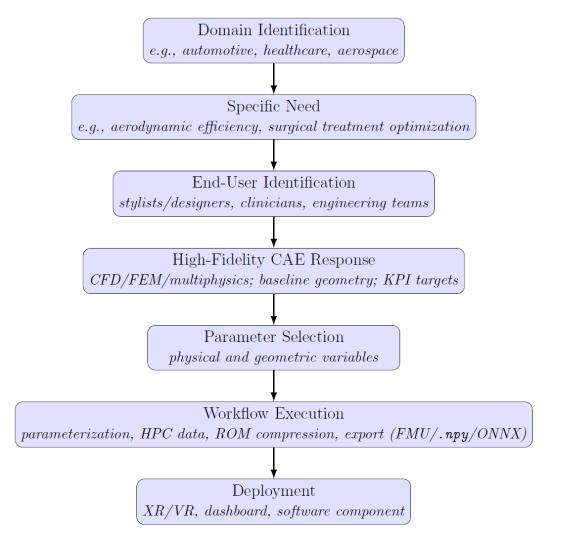
- FMU are translated to ARM
- Meta Quest 3
- Input parameters are controlled by hands
- We can add an immersive scene
- Wireless AR/VR







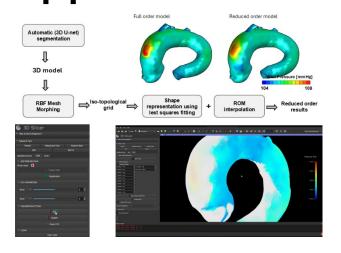
CAE agnostic approach

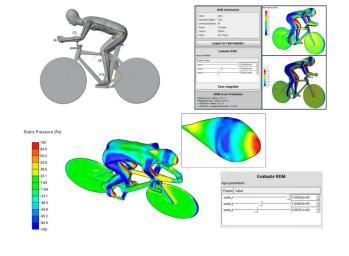


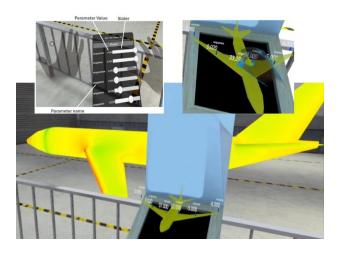


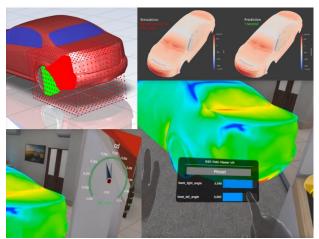


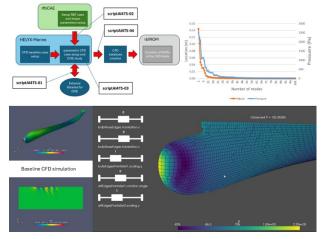
Interactive Real-Time Design Exploration: Applications

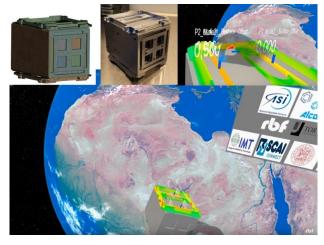


















Medical Digital Twins

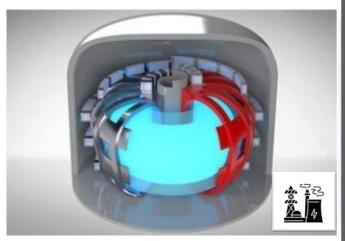
Research Projects and Applications



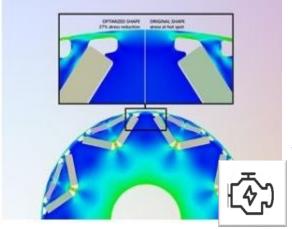


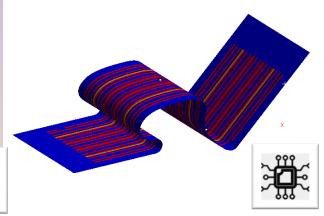
Research and Industrial sectors

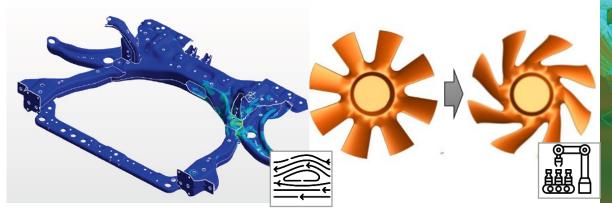


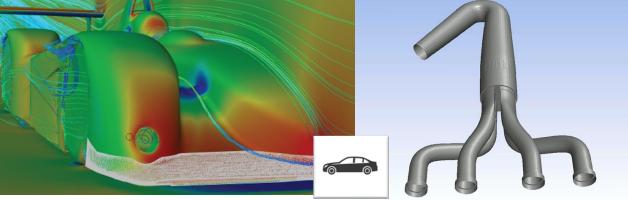














EU-funded research projects 2013-2025

























Running projects on healthcare

- Fortissimo Plus Business Experiment PANDORA - Pre-operative Assistant Based on Data-Driven Approaches for Vascular Grafts Surgery
- EU-funded Cyber 4.0 competence center SafeBot4Twin - A Large Language Modelbased Cyber-secure chatbot to control Medical Digital Twins
- NextGenerationEU iNEST project ROMed2VR - Virtual Reality Empowered by Computational Fluid Dynamics Reduced Order Models to Support Pre-Surgery Medical Planning











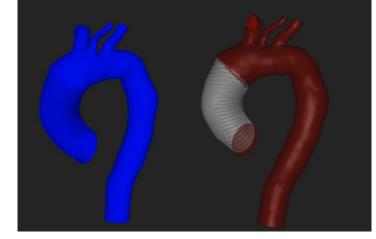






PANDORA





PANDORA

Pre-operative AssistaNt based on Datadriven apprOaches for vasculaR grAft surgery

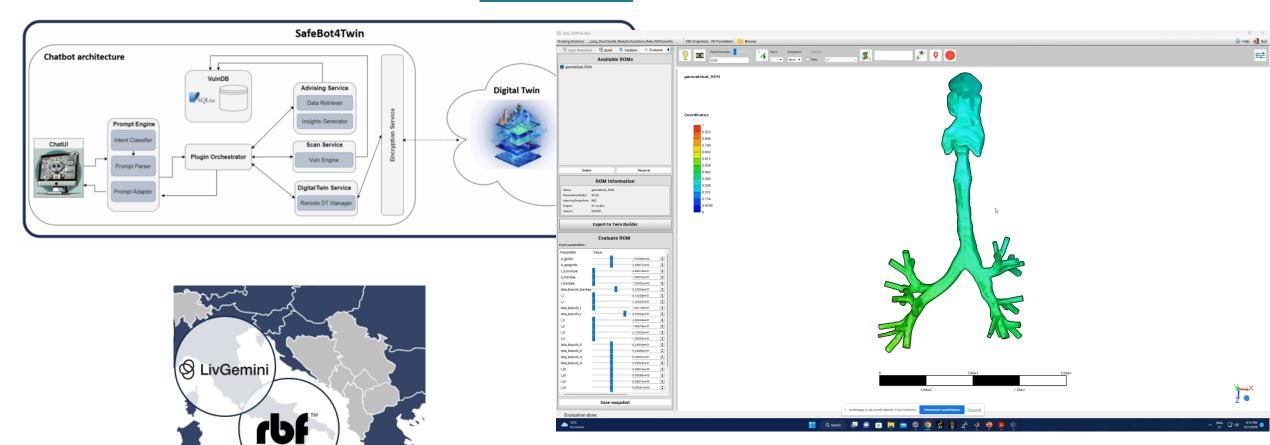






SafeBot4Twin CYBER 4.0 CYBER 4.0 CYBER SECURITY COMPETENCE CENTER











Interactive Medical Digital Twins in 3d Slicer

Meditate ESR02 – Leonardo Geronzi

https://meditate-project.eu/esr-02-leonardo-geronzi/

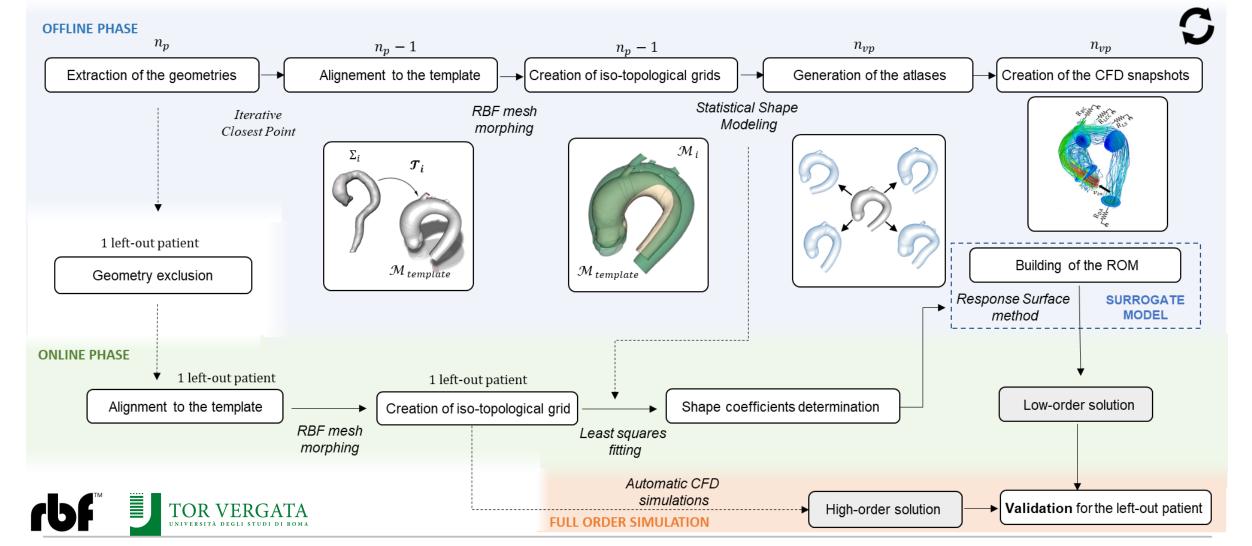




Hemodynamic prediction based on surrogate modeling



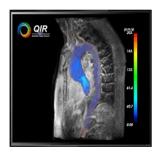


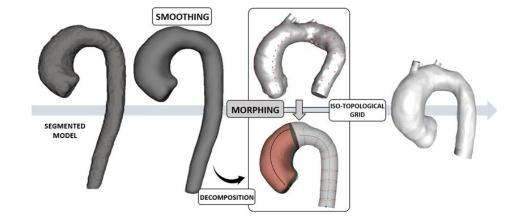




The offline phase

MRI 4D Flow





Based on principal component analysis (PCA)

Each shape $\widetilde{M_S}^i$ can be built combining n_{SM} eigenvalues λ_j and n_{SM} eigenvectors $\boldsymbol{W_j}$

$$\widetilde{M_S}^i = M_{S_{mean}} + \sum_{j=1}^{n_{SM}} c_j^i \sqrt{\lambda_j} \mathbf{W}_j$$

Automatic (3D U-net) segmentation methods developed by Marin-Castrillon et al. [11]



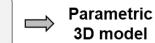


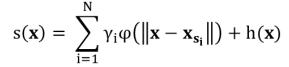
⇒ 3D model ⇒











In the 3D space:

$$\mathbf{x_{node_{new}}} = \mathbf{x_{node}} + \begin{bmatrix} \mathbf{s_{x}}(\mathbf{x_{node}}) \\ \mathbf{s_{y}}(\mathbf{x_{node}}) \\ \mathbf{s_{z}}(\mathbf{x_{node}}) \end{bmatrix}$$

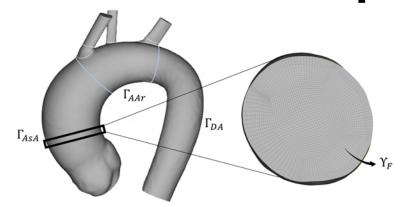








The offline phase

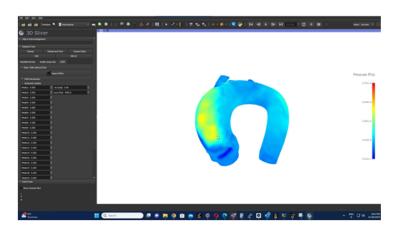


1) DECOMPOSITION

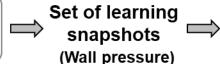
Proper orthogonal decomposition (**POD**) techniques:

$$\Omega = U\Sigma V^T$$

$$\min_{\mathbf{\Phi}} \left\| \mathbf{\Omega} - \mathbf{\Phi} \mathbf{\Phi}^{\mathsf{T}} \right\|^2$$



CFD Simulation using the synthetic data created through SSM



Model order reduction techniques



Surrogate Model

Surrogate model deployment

Navier-Stokes equations:

$$\mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho} \nabla \mathbf{p} + \nu \nabla^2 \mathbf{u}, \text{ in } \Upsilon_{F}$$
$$\nabla \cdot \mathbf{u} = 0, \text{ in } \Upsilon_{F}$$

SIMPLE pressure-velocity coupling

Parameteric velocity inlet – pressure outlet BCs

TOR VERGATA

UNIVERSITÀ DEGLI STUDI DI ROMA

2) INTERPOLATION

Genetic Aggregation Response Surface (GARS) technique for the ROM interpolation



Geometrical parameters Physical parameters



FMU DEPLOYMENT Model Exchange 2.0



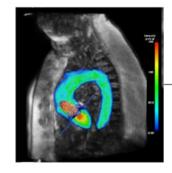
Excluded patient)

Automatic (3D U-net) segmentation

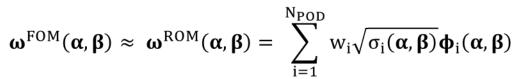


3D model





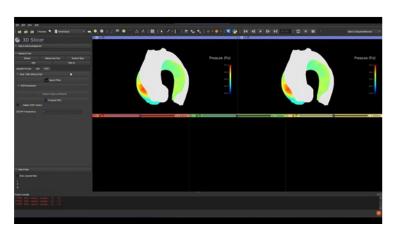
Inlet BC velocity value from the images



RBF Mesh Morphing



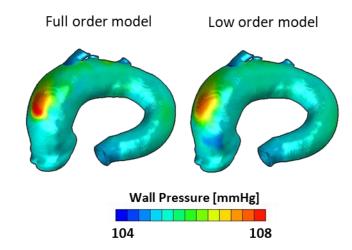
Shape representation using lest squares fitting

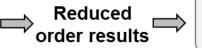


ROM

interpolation







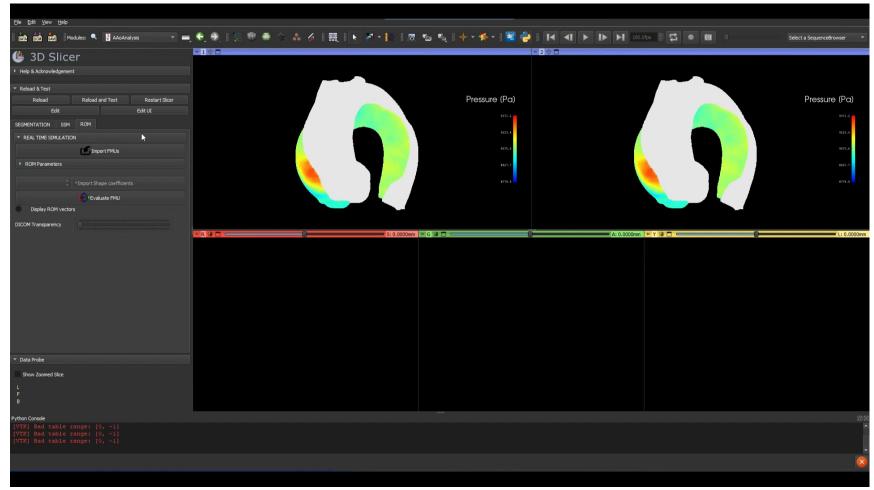
Comparison full order vs reduced order simulation

$$e_{ROM}^{rel,i-out} = \frac{\left\|\boldsymbol{\omega_{i-out}^{FOM}} - \boldsymbol{\omega_{i-out}^{ROM}}\right\|}{\left\|\boldsymbol{\omega_{i-out}^{ROM}}\right\|}$$

$$e_{ROM}^{abs,i-out} = max \big(\big\| \boldsymbol{\omega_{i-out}^{FOM}} - \boldsymbol{\omega_{i-out}^{ROM}} \big\| \big)$$



The online phase









Support to shunting procedures

From Copernicus to ROMed2VR

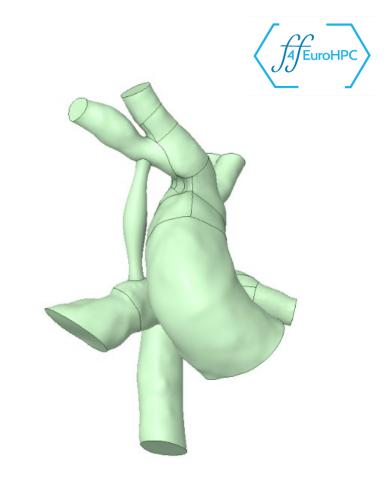






Copernicus

- Cloud-Based HPC Platform to Support Systemic-Pulmonary Shunting Procedures
- Congenital Heart Diseases (CHDs) = ~1/3 of all birth defects
- Modified Blalock Taussig Shunt (mBTS)
- Common palliative surgery for cyanotic CHD
- High risk: **over-shunting** & **shunt thrombosis** significant mortality
- **Need**: better tools to support surgical planning & improve outcomes



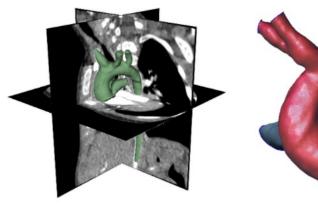




Copernicus

- Patient-specific digital twin (MDT) built via advanced CFD simulations
- Runs on cloud-based **HPC**: reliable & costefficient
- Reduced Order Model (ROM) of vascular district with shunt parameterization
- Interactive web interface for medical staff to explore scenarios
- Impact: Affordable **decision-support** tool, safer, tailored mBTS interventions



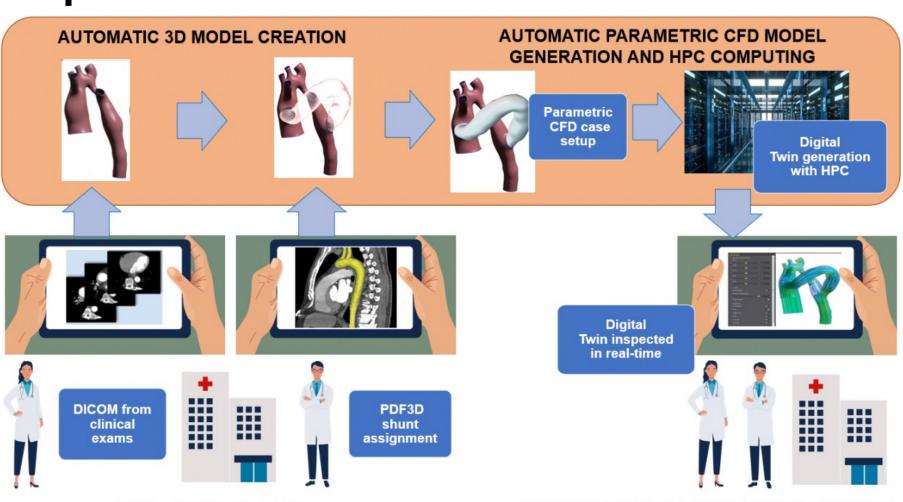






Medical Digital Twin Copernicus









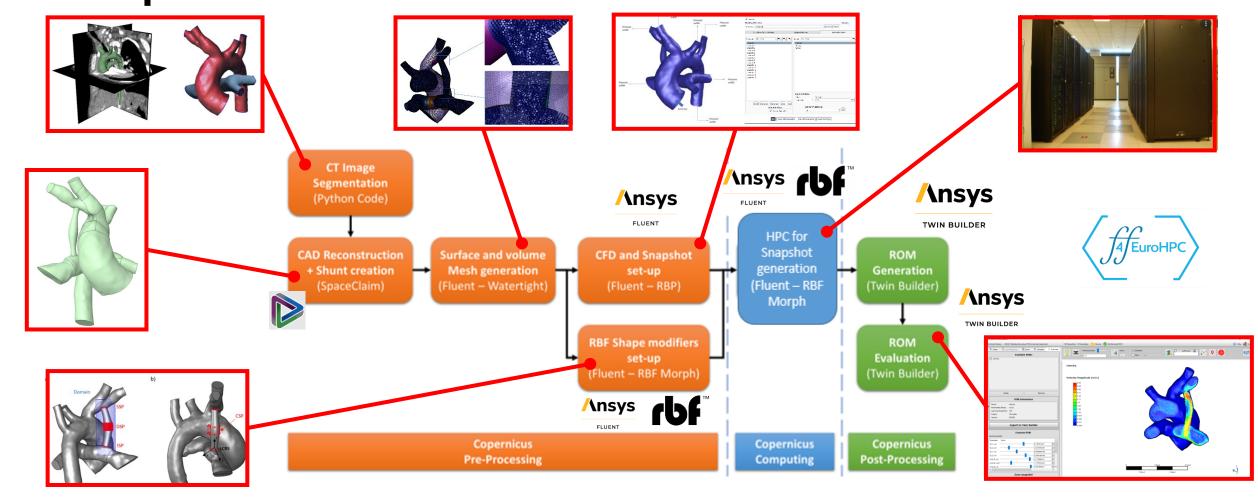






Medical Digital Twin Copernicus



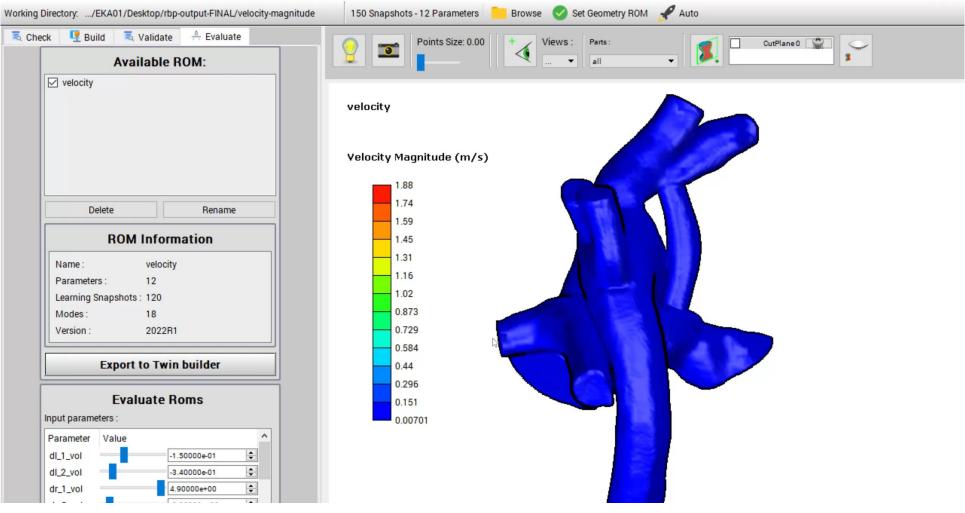






Medical Digital Twin Copernicus









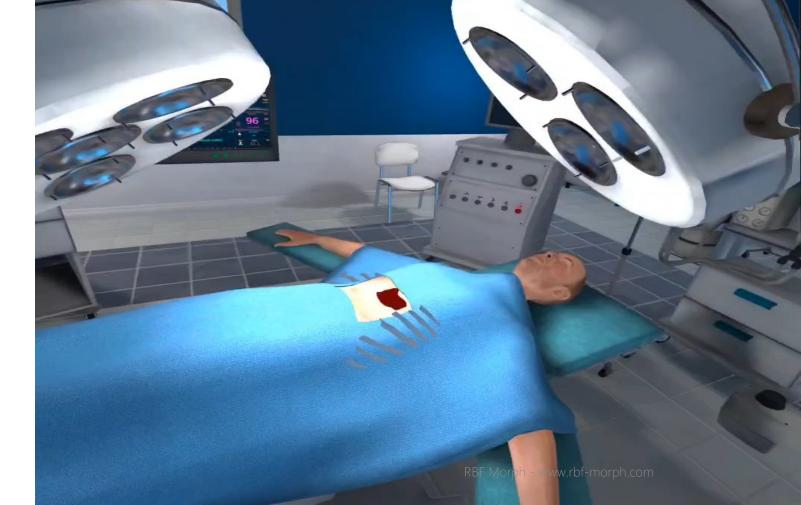
Next step?

A complete solution to deliver interactive digital twins with AR/VR custom UI



- FMU are translated to ARM
- Meta Quest 3
- Apple Vision Pro (very soon!)
- Input parameters are controlled by hands





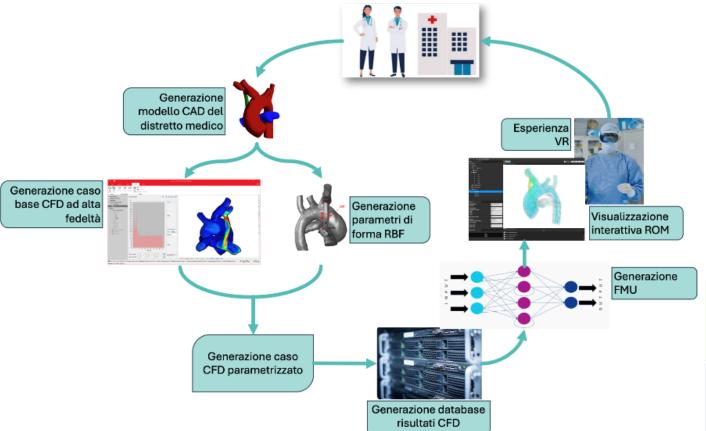


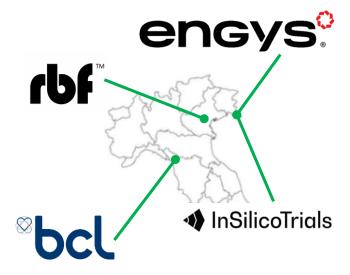


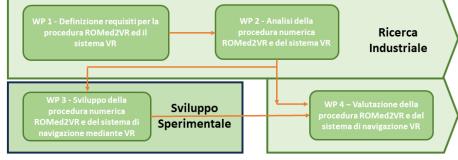


ROMed2VR inest





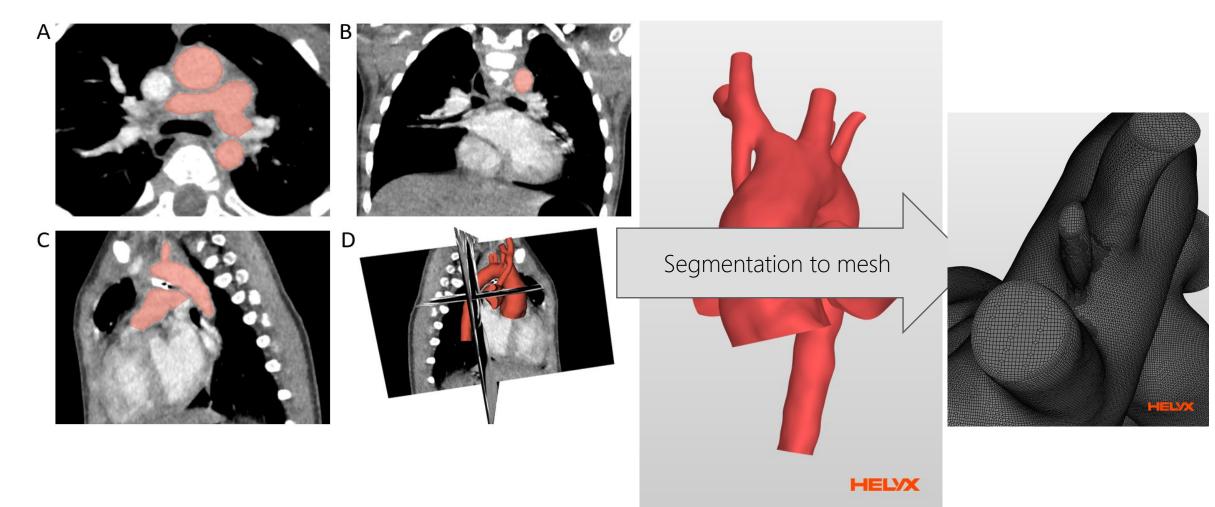








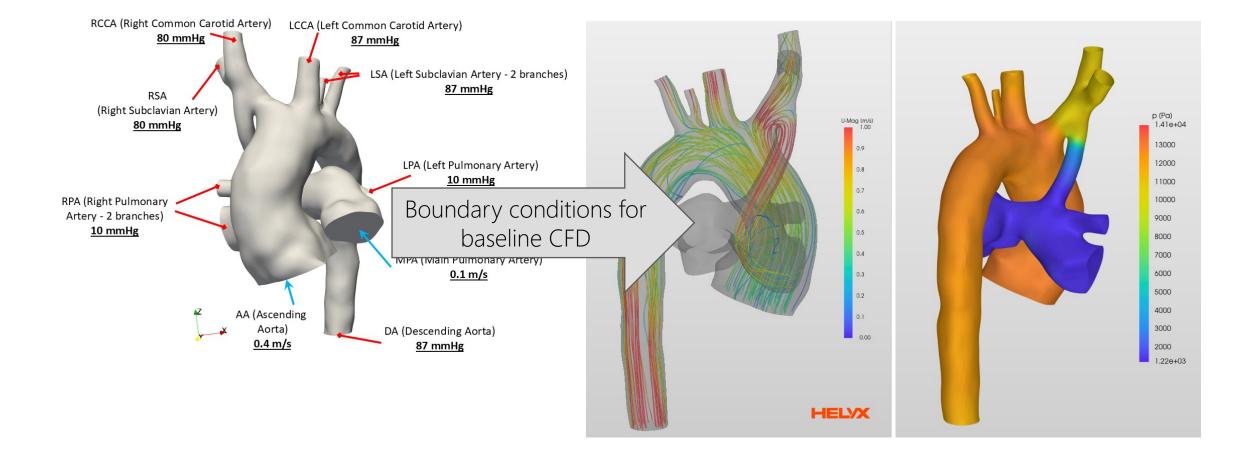










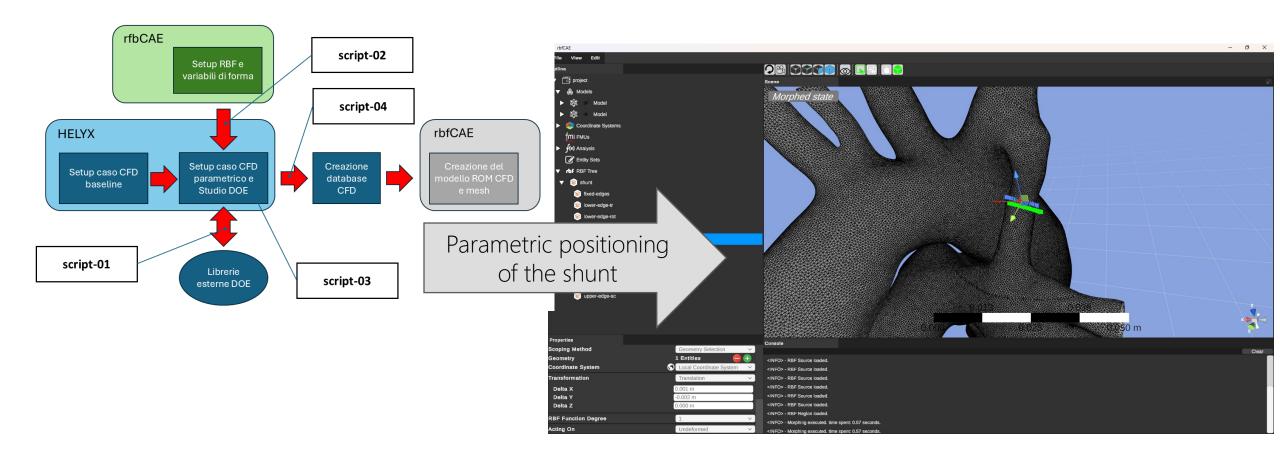








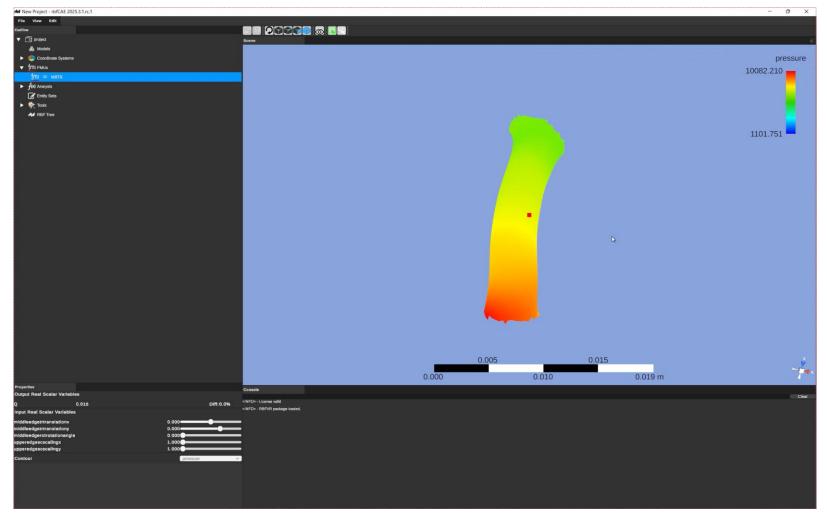




























RBF Morph technologies

A complete solution for Medical Digital Twins



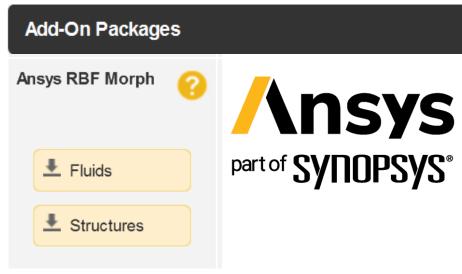


Ansys RBF Morph

- An RBF mesh morphing solution fully embedded in Ansys
 - Ansys RBF Morph Fluids an Add On for Fluent
 - Ansys RBF Morph Structures an ACT App for Mechanical
- Full integration with optiSLang and Twin Builder
- Support for LS-DYNA and APDL



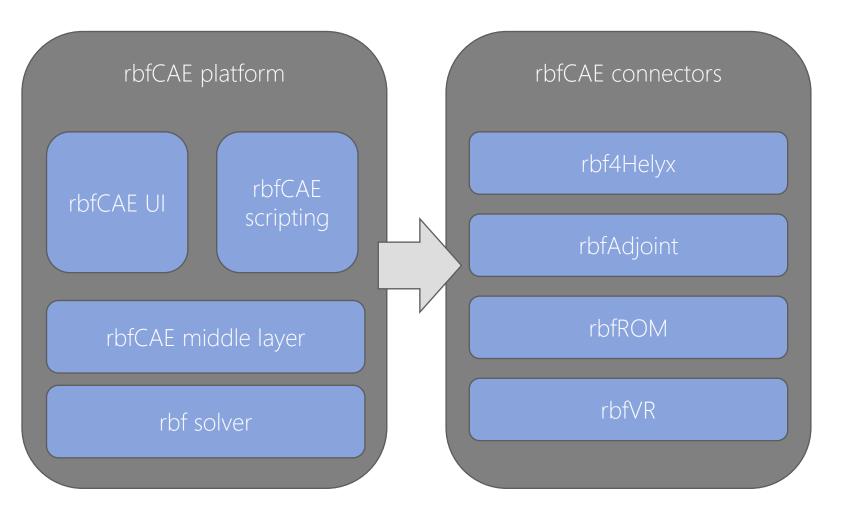








rbfCAE solution



- Released in 2024
- Read in STL, STEP
- Unity -OpenCascade
- Solver independent process that supports many mesh formats
- Scriptable via python







Conclusions

- Interactive Digital Twins? Yes!
- We can deploy fast interactive ROM on VR and on custom dashboards
- We use RBF both for the geometrical intelligence and both for the Al inference
- Multiple workflow are supported: a variety of CAE software can be combined to mesh morphing to generate synthetic datasets
- The approach works both for parametric cases (shapes are varied according to specific actions) both for SSM (shapes are collected from a cohort of data)





Many thanks for your attention!

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