



Advanced radial basis function mesh morphing of RBF Morph for LS-DYNA enabled in Ansys Mechanical.



Marco Evangelos Biancolini, CTO & Company Founder, RBF Morph srl marco.biancolini@rbf-morph.com





Media partner

rbf



rbf

Outline

- RBF Morph technology and software solutions for **shape optimization**
- Mesh morphing needs for crashworthiness in the automotive industry
- A workflow based on LS-DYNA solver, Ansys Mechanical and RBF Morph
- Industrial example: exploring how a car bonnet can be reshaped
- Conclusions







LS-DYNA









10+ years of RBF Morph



rbf

Industries served (100+ institutions)







Radial Basis Functions mesh Morphing

- We offer Radial Basis
 Functions (RBF) to drive mesh morphing (smoothing) from a list of source points and their displacements
 - Surface shape changes
 - Volume mesh smoothing
- RBF are recognized to be one of the **best mathematical tool** for mesh morphing

$$\begin{cases} s_x(\mathbf{x}) = \sum_{i=1}^N \gamma_i^x \varphi(\|\mathbf{x} - \mathbf{x}_{s_i}\|) + \beta_1^x + \beta_2^x x + \beta_3^x y + \beta_4^x z \\ s_y(\mathbf{x}) = \sum_{i=1}^N \gamma_i^y \varphi(\|\mathbf{x} - \mathbf{x}_{s_i}\|) + \beta_1^y + \beta_2^y x + \beta_3^y y + \beta_4^y z \\ s_z(\mathbf{x}) = \sum_{i=1}^N \gamma_i^z \varphi(\|\mathbf{x} - \mathbf{x}_{s_i}\|) + \beta_1^z + \beta_2^z x + \beta_3^z y + \beta_4^z z \end{cases}$$



Biancolini, M. E. (2017). *Fast radial basis functions for engineering applications*. Springer International Publishing.

Parametric CAE models

rbf^{**}

CAE models supported includes flow analysis (CFD) and structural analysis (FEM)

RBF Morph makes the CAE model parametric with respect to the shape.

Works for any size of the mesh.

Shape parameters can be steered with the optimizer of choice.





- It's **easy and fast**: shape parameters are defined in the CAE GUI. No need to iterate the CAD
- The turnaround time of the optimization is usually **reduced by a factor five** (weeks become days)

We offer Ansys integrated solutions...



ACT Extension (FEM)

- Released in 2014
- Fully embedded in ANSYS Mechanical (parametric)
- Benefits of underlyiin geometry (or aux ge with dead meshes)
- ...WB Meshing

	Add-On Packages	
	nCode	RBF Morph 🕜
	Full Package	Full Package
(rbf-morph)		gacy ACIS
RBF Morph A	ст 👝 🔽	D
Extension for	chf	Full Package
Mechanical		
Target Application: Meshing		

Fast RBF mesh morphing technology that makes the mesh shape parametric with a few clicks. Basic and hierarchical shape modifications defined in the tree. Automatic shape optimisation now included.



Fluent Module (CFD)

- Released in 2009
- Fully integrated within Fluent (GUI, TUI & solving stage), Workbench and Adjoint Solver
- Multi physics features
 (FSI)

SIMULATIONSUMMIT connect



...and a Stand Alone software



- Released in 2011
- Read in STL and CGNS file formats
- Solver independent process that supports many mesh formats
- Scriptable via tcl



rbf

Some examples of mesh morphing for mechanical applications







https://youtu.be/Txd6gvkhko0

SIMULATIONSUMMIT connect

Mesh morphing needs in the automotive industry

- Explore **shape variants** without recreating a new model
- **Reuse** the FEA model of a similar car at early stage design of a new car
- Mesh morphing requirements
 - Perfect matching between style surface and morphed FEM
 - Same platform (hinges, connections).
 - Keep same cross section
 - Geometrical constraints (preserve welding)
 - Discontinuities are not acceptable



/\nsys

LS-DYNA



7bF



Combined usage of both the ACTs





Direct shape changes within the Ansys Workbench Environment

Ability to quickly edit LS-DYNA keyword files

Flexible and easy to use with a consistent ANSYS-like user interface





Demonstration case of a car bonnet



Honda Accord 2011 model

https://www.nhtsa.gov/crash-simulation-vehicle-models

• Starting from a LS-DYNA keyword file









3 Solid body 11 Surface Body





SIMULATIONSUMMIT connect

All in LS-DYNA-Workbench environment!

Name



Details of "RBF Target"	
-------------------------	--

Node Selection	
Scoping Method	Geometry Selection
Geometry	12 Bodies
General	
Transformation	Translation
Translation Definition	Manual
Delta x	0 m
Delta y	0 m
Delta z	0 m
- RBF Function	
Degree	1
Combine Select	
Acting On	Undeformed
If Selected Nodes Overlap	Override
Coord Filtering	No
BRBF Problem	
Source	38473
Target	42655
-	

🛶 🗸 🐚 Surface Body	/ 5(External Model)
🛶 🔪 🖏 Surface Body	6(External Model)
🔤 🗸 🖏 Surface Body	7(External Model)
Surface Body	8(External Model)
Surface Body	9(External Model)
Surface Body	10(External Model)
Surface Body	/ 11(External Model)
Global Coordinate	System
Bot Bonnet	oyutem.
Connections	
Mesh	
Named Selections	<u> </u>
Brown RBF Morph Set Up	
🖃 🖓 RBF Target	
RBF Source	
FIRE REF Morph Update	1
)
Thitial Conditions	
	/
Analysis Settings Solution (BS) Solution Info	rmation
Analysis Settings Solution (B5) Solution (B5) Solution Info	rmation
Coping Method	rmation Geometry Selection
Coping Method Scoping Method Scoping Method Scoping Method Scoping Method	Geometry Selection 16 Faces
Comparison of the settings C	Geometry Selection 16 Faces
Communication of the settings	Geometry Selection 16 Faces Rotation
Communication of the settings Communication of the settings Solution (BS) Communication of the settings Solution Info Setting of the sett	Geometry Selection 16 Faces Rotation By Coordinate System
Analysis Settings Solution (BS) Solution Info settings Solution Info solution solution Info solution solution Info solution solution Info solu	Geometry Selection 16 Faces Rotation By Coordinate System 45 *
etails of "RBF Source" Node Selection Scoping Method Geometry General Transformation Rotation System Definition Angle Coordinate System	Geometry Selection 16 Faces Rotation By Coordinate System 45 * Rot_Bonnet
Coordinate System Axis Used	Geometry Selection 16 Faces Rotation By Coordinate System 45 ° Rot_Bonnet Y
Coordinate System Arayles Settings Solution (BS) Solution Info Solu	Geometry Selection 16 Faces Rotation By Coordinate System 45 * Rot_Bonnet y
Coordinate System Axis Used RBF Function Degree	mation Geometry Selection 16 Faces Rotation By Coordinate System 45 * Rot_Bonnet Y 1
Conditional System Conditional System Conditional System Conditional System Conditional System Coordinate System Axis Used RBF Function Degree Combine Select	Geometry Selection 16 Faces Rotation By Coordinate System 45 * Rot_Bonnet y 1
Combine Select	Geometry Selection 16 Faces Rotation By Coordinate System 45 * Rot_Bonnet y 1 Undeformed
Condition System Analysis Settings Solution (BS) Solution Info Scoping Method General Transformation Rotation System Definition Angle Coordinate System Axis Used RBF Function Degree Combine Select Acting On If Selected Nodes Overlap	Geometry Selection 16 Faces Rotation By Coordinate System 45 ° Rot_Bonnet Y 1 Undeformed Override
Analysis Settings Solution (BS) Solution (BS) Solution Info etails of "RBF Source" Node Selection Scoping Method Geometry General Transformation Rotation System Definition Angle Coordinate System Axis Used RBF Function Degree Combine Select Acting On If Selected Nodes Overlap Coord Filtering	rmation Geometry Selection 16 Faces Rotation By Coordinate System 45 * Rot_Bonnet y 1 Undeformed Override No
Conditional of the settings Control of the settings Solution (BS) Control of the settings Solution (BS) Control of the settings Solution Info Setection Scoping Method Geometry General Transformation Rotation System Definition Angle Coordinate System Axis Used RBF Function Degree Combine Select Acting On If Selected Nodes Overlap Coord Filtering RBF Problem	mation Geometry Selection 16 Faces Rotation By Coordinate System 45 ° Rot_Bonnet y 1 Undeformed Override No

38473

Target

▼ Search Outline V

Solid Body 1(External Model)

Solid Body 2(External Model)

Solid Body 3(External Model)

Surface Body 2(External Model)

🖳 🖕 Surface Body 4(External Model)

Moving surface: rotation



rbf





We can stretch it preserving its supporting bodies !













In an instant, we can narrow it down a lot!











 We can change the shape of the bonnet altering its concavity using a similar geometric model!





Obviously preserving the quality of the mesh...





SIMULATIONSUMMIT connect

rbf

• Everything to have a model ready to be run through LS-DYNA







Example of results

rbf

CRASH TEST: STARTING MODEL

CRASH TEST: NEW MORPHED MODEL

SI







- There is a need for advanced tools to explore **shape variants** in the crashworthiness field
- Mesh morphing sounds as a good tool to reuse existing and validated FEA models
- In this study we presented a new approach based on LS-DYNA, Ansys Mechanical and RBF Morph that allows to predict the crash of a reshaped car bonnet without the need of a new FEA mesh
- Easy design and shape optimization coupled with LS-DYNA explicit solver
- Working with AUTODYN and LS-DYNA@LS-DYNA solver settings
- Faster morphing only in one Component Model
- Intuitive and **same UI** of RBF Morph in Mechanical
- The proposed method was able to adapt the bonnet of a sedan onto the one of a pick-up



SIMULATIONSUMMIT_{connect}





Thank you!

marco.biancolini@rbf-morph.com



linkedin.com/company/rbf-morph



youtube.com/user/RbfMorph



rbf-morph.com

Organizzato da



Media partner

